

Confluence of Shallow Right-Linear Systems

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Rewrite Systems

Define a binary relation over a set of terms

Two main interpretations:

- Model of some dynamical system:

set of terms \mapsto state space

rewrite relation \mapsto dynamics

- Defining an equational theory

set of terms \mapsto elements in the model of the theory

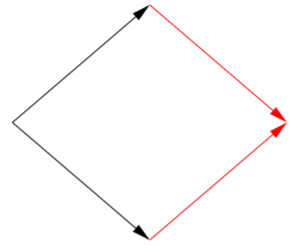
rewrite relation \mapsto equational identities in the theory: simplification

Confluence

Two main properties of rewrite systems: confluence and termination

Confluence: Interpretations–

- Model of some dynamical system: a general definition of determinism
- Equational reasoning: decide word problem, assuming termination



Known Results

Class	Reachability	Confluence	Comment
General TRS	undecidable	undecidable	Turing-complete
Shallow TRS	undecidable	?	[Jacquemard 2003]
Linear TRS	undecidable	?	
RL-FPO TRS	decidable	?	[Takai, Kaji, Seki 2000]
Shallow RL	decidable	decidable	This work
Shallow Linear	decidable	decidable	[Godoy, T, Verma 2003]
Ground TRS	decidable	decidable	PTime [Godoy+ 00, T 01]

Shallow Right Linear Rewrite Systems

- Shallow: All variables occur at depth at most one
- Right Linear: Variables are not repeated on the RHS terms

Example of a shallow right-linear rewrite system:

$$R = \{x \vee x \rightarrow x, x \vee y \rightarrow y \vee x, x \vee 0 \rightarrow x, x \vee 1 \rightarrow 1\}.$$

Results for shallow right-linear systems:

- Word problem is decidable [Comon+94, Niu96]
- Reachability and joinability are decidable [Takai+00]

Approach

R is confluent if

$$\forall s, t : s \leftrightarrow_R^* t \Rightarrow \exists u. s \rightarrow_R^* u \leftarrow_R^* t$$

Instead of checking for all s, t , we reduce the check to terms s, t from a finite set, but with respect to a slightly modified \bar{R} .

Key Idea 1: Finite set consists of constants, variables and top-stable flat terms

Top Stable Terms

A term is top-stable if it cannot be rewritten to a constant/variable.

Example: $x \vee y$ is top-stable, whereas $x \vee 1$ is not.

Why are top-stable terms important for confluence?

If s, t are not top-stable, then $\exists \alpha, \beta$ s.t.

$$s \rightarrow_R^* \alpha, \quad t \rightarrow_R^* \beta.$$

If s, t are equivalent, then so are α, β . But we explicitly check for joinability of all equivalent α, β .

Problem: There are infinitely many top-stable terms.

Top Stabilizable Constants

A constant that is R -equivalent to a top-stable term.

Why are top-stabilizable constants important for confluence?

Sup. c is top-stabilizable and top-stable s is equivalent to c :

Given	Need to check
$u[c] \leftrightarrow^* v$	$u[c] \downarrow v$
$u[s] \leftrightarrow^* v$	$u[s] \downarrow v$
$u[\bar{c}] \leftrightarrow_{\bar{R}}^* v$	$u[\bar{c}] \downarrow_{\bar{R}} v$

Top-stabilizable c should not be used in the joinability proof. Why?

Shallow Right-Linear TRSs

Confluence preserving transformation:

Shallow right-linear \mapsto Flat right-linear

Flat TRSs can only use depth zero terms or non-top-stable terms in rewrite derivations.

Example. Unused subterms can be generalized:

$$\begin{array}{l} (x \vee y) \vee (z \vee 1) \rightarrow (x \vee y) \vee \underline{1} \rightarrow x \vee y \rightarrow y \vee x \\ w \vee (z \vee 1) \rightarrow w \vee \underline{1} \rightarrow w \rightarrow^* w \end{array}$$

Example: Useless positions can be generalized:

$$1 \rightarrow (x \vee y) \vee 1 \mapsto 1 \rightarrow z \vee 1$$

Extending R to \bar{R}

Fixpoint computation: Incrementally add \bar{c} for constants c that can be detected to be top-stabilizable.

$$\begin{aligned} R_0 &= R \\ R_{i+1} &= R_i \cup \{c \rightarrow \bar{d} : c, d \in \Sigma_0, \exists \text{ flat term } t \in \mathcal{T}(\Sigma \cup \bar{\Sigma}_0, \mathcal{V}) : \\ &\quad t \leftrightarrow_{R_i}^* c \leftrightarrow_R^* d, t \text{ is top-stable wrt } R_i\} \\ \bar{R} &= \bigcup_i R_i \end{aligned}$$

If $c \rightarrow \bar{d} \in \bar{R}$, then d is top-stabilizable.

Detecting Top-Stabilizable Constants

Key Idea 2: The detection of top-stabilizable constants is related to the “confluentness” of R .

Let R be confluent upto height h :

—i.e., any set of equivalent terms with height $\leq h$ is joinable.

Then, if t is a top-stable term with height $\leq h + 1$ and equivalent to c , then t is detected:

—i.e., $c \rightarrow \bar{d} \in \bar{R}$ for some $\bar{d} \in \bar{\Sigma}_0$.

Confluence Characterization

R is confluent iff the following two conditions hold:

- (i) Every R -equivalent set of constants is R -joinable.
- (ii) Let $\{\alpha_1, \dots, \alpha_k, t_1, \dots, t_n\}$ be an \overline{R} -equivalent set of terms, where
 - $\alpha_i \in \Sigma_0 \cup \mathcal{V}$, and
 - t_i are top-stable flat terms wrt \overline{R} .Then, $\exists t'_1, \dots, t'_n$ s.t.
 - every t'_i is either t_i or \bar{c} or x ,
 - some t'_i coincides with t_i , and
 - the set $\{\alpha_1, \dots, \alpha_k, t'_1, \dots, t'_n\}$ is \overline{R} -joinable.

Example

$R = \{x \vee x \rightarrow x, x \vee y \rightarrow y \vee x, x \vee 0 \rightarrow x, x \vee 1 \rightarrow 1\}$.

- $0 \not\leftrightarrow^* 1$ and $0 \not\leftrightarrow^* x$ and $1 \not\leftrightarrow^* x$.

Hence, condition (i) is vacuously true.

- Any term equivalent to 0 rewrites to 0. Same for 1 and x .

Hence, none of 0, 1, and x are top-stabilizable.

$\therefore \bar{R} = R$.

- The set $\{x \vee y, y \vee x\}$ is the only equivalent set of flat top-stable terms.

But, this is joinable.

Hence, condition (ii) is also true.

- Hence, R is confluent.

Proof Idea

\Leftarrow : If conditions (i) and (ii) are true, then

- R is confluent and
- all top-stabilizable constants are detected.

- Pick the minimal witness; it is either witness for
(a) to nondetection of top-stable term.
(b) to nonconfluence, or
- If (a), then we can get a smaller witness for nonconfluence. \perp .
- If (b), then it can be mapped to a set of the form covered by condition (ii).

\Rightarrow : Project derivation of R -joinability onto \overline{R} -joinability over flat terms.

Main Result

Confluence of shallow and right-linear term rewrite systems is decidable.

- Flatten R into a flat right-linear system
- Detect top-stabilizable constants and construct \overline{R}
- Check all equivalent constants are R -joinable
- Compute all sets of equivalent flat top-stable terms. Test if they are joinable, according to condition (ii)
- All above steps are possible because equivalence, reachability, and joinability are decidable for R and \overline{R}

Reflections

- Decidability of confluence for shallow right-linear systems is very surprising
- Proof is technical, but the high-level proof is similar to those for the special cases
Each generalization is getting exponentially harder
- Crucial points for confluence of a TRS class:
 - Is equivalence decidable?
 - Reachability and joinability used as black-box?
 - Is the class asymmetric?
- Open problem: Confluence of RL-FPO systems.