Satisfiability Modulo Theories and Assignments

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Uni. degli Studi di Verona - CNRS - SRI International

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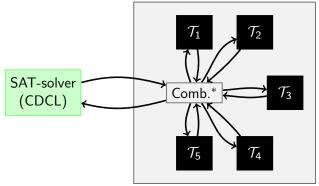
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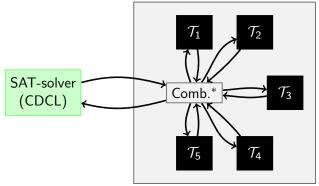


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* e.g. equality sharing / Nelson-Oppen [NO79] The material presented here departs from this picture. Motivation: conflict-driven reasoning Combining conflict-driven reasoning mechanisms

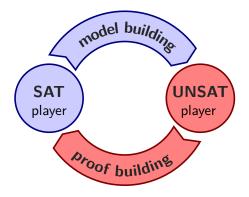
The CDSAT framework

Termination, Soundness and Completeness

1. Combining conflict-driven reasoning mechanisms

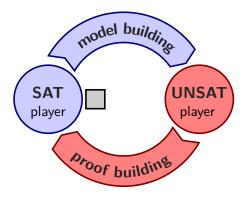
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It involves a trail where a putative model is being described.



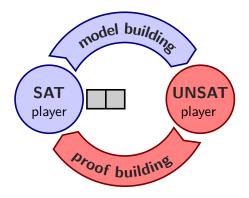
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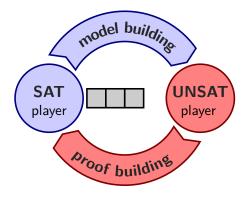
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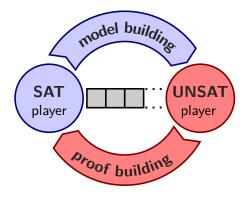
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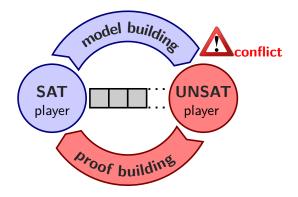
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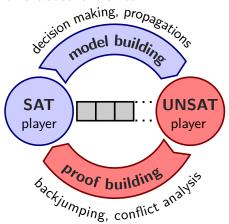


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Archetype of conflict-driven reasoning: CDCL

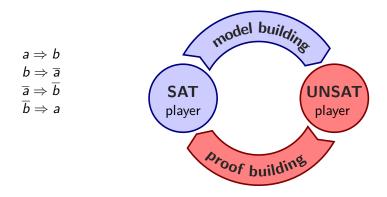


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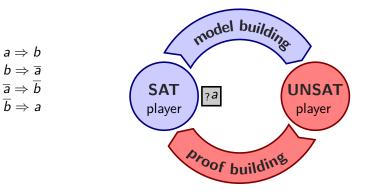


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a conflict occurs when a clause is falsified

SAT player Player Player Player

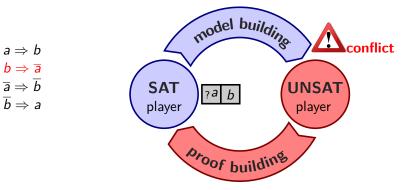
 $a \Rightarrow b$ $b \Rightarrow \overline{a}$ $\overline{a} \Rightarrow \overline{b}$ $\overline{b} \Rightarrow a$

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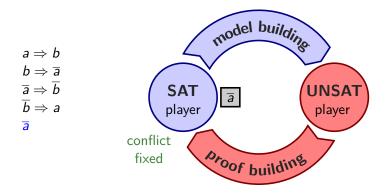


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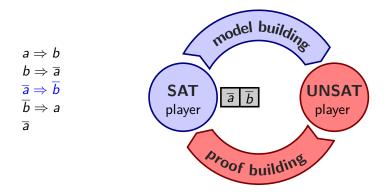


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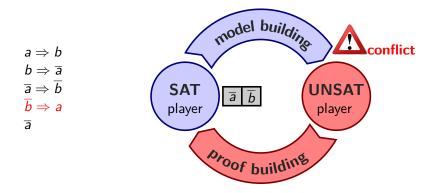


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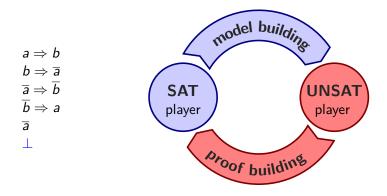


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Conflict-driven reasoning can be used for (other) theories

Examples:

- LPSAT [WW99]
- Separation logic [WIGG05]
- Linear Rational Arithmetic [MKS09, KTV09, Cot10]
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These conflict-driven decision procedures for \mathcal{T} -satisfiability

- ► use assignments to first-order variables (e.g. x ← 3/4) like CDCL uses Boolean assignments to Boolean variables;
- may explain conflicts by introducing atoms that are not in the input.

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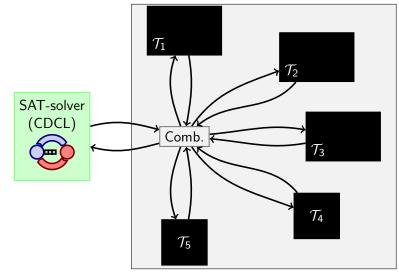
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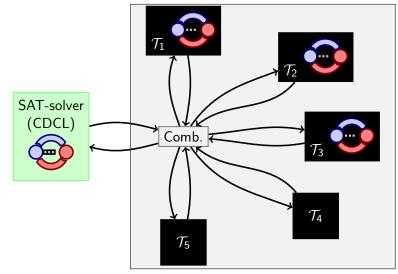
- ▶ Now undo the guess but keep *I*₃.
- and so on...

(when there is no guess to undo, problem is UNSAT)

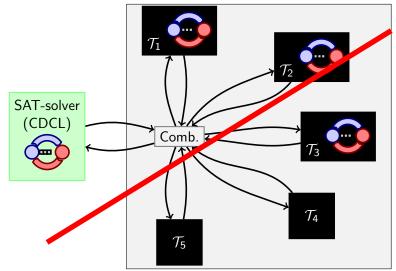
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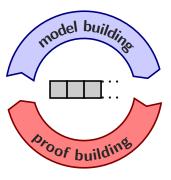
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Missing out on tighter integration possibilities, which overcome some limitations of the $\mathsf{DPLL}(\mathcal{T})$ interfaces

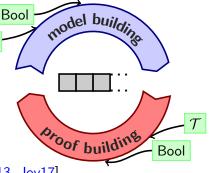
A recent approach: MCSAT (Model-Constructing Sat.)

- MCSAT, introduced in [dMJ13, JBdM13],
 - departs from the $\mathsf{DPLL}(\mathcal{T})$ architecture
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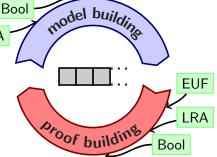


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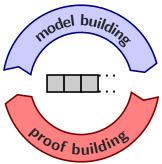
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+ Equality with Uninterpreted Functions (EUF) [JBdM13] Other MCSAT contributions: bit-vectors [ZWR16, GLJ17]

- Boolean theory can have the same status as other theories.
- ► Natively overcomes some limitations of the (basic) DPLL(T) interfaces:
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Model-constructing sat. / Conflict-driven reasoning

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Left to be determined:

the interpretation of variables and uninterpreted symbols.

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 In particular, what about theories for which we have a black
 box fit for the equality-sharing / Nelson-Oppen scheme?
 Is there a way to integrate or generalize both MCSAT and the
 equality sharing scheme?

The answer: CDSAT

We answer these questions in a framework called **CDSAT** for Conflict-Driven Satisfiability.

- ► CDSAT generalises conflict-driven reasoning to generic combinations of disjoint theories T₁,..., T_n
- ► CDSAT solves the problem of combining multiple conflict-driven T_k-satisfiability procedures into a conflict-driven (Uⁿ_{k=1} T_k)-satisfiability procedure
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- CDSAT can integrate black-box procedures, and reduces to the equality-sharing scheme if only such procedures are used

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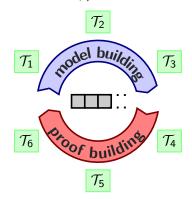
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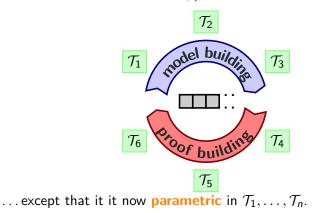
We identify sufficient requirements on theory reasoning modules for the combined system to be sound, complete, and terminating.

2. The CDSAT framework

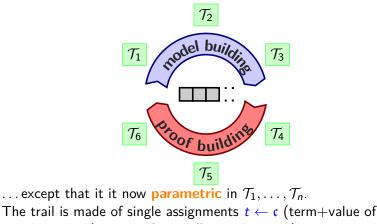
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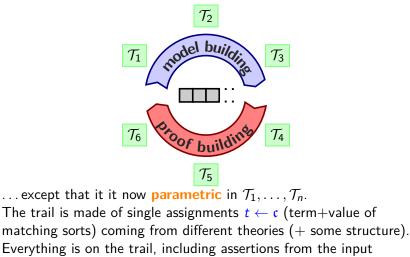
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problem (e.g. $C \leftarrow true$ for an input clause C)

For each theory \mathcal{T} to combine, and each sort that it knows of, we must specify a **pool of** \mathcal{T} -values to use in assignments: e.g., if we want to solve $(x \cdot x \simeq 2)$, we may want to write $x \leftarrow \sqrt{2}$.

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Exception:

every theory uses the two values true and false for sort Bool

When combining \mathcal{T} and \mathcal{T}' , if \mathcal{T} writes $u \leftarrow \mathfrak{c}$ on the trail, what can \mathcal{T}' understand from it?

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Similarly if \mathcal{T} writes $u_1 \leftarrow \mathfrak{c}_1$ and $u_2 \leftarrow \mathfrak{c}_2$ with two distinct values, \mathcal{T}' understands the trail as if it contained $u_1 \not\simeq u_2$.

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Exception: all theories understand Boolean assignments

A set of inferences of the form

$$t_1 \leftarrow \mathfrak{c}_1, \ldots, t_k \leftarrow \mathfrak{c}_k \vdash I \leftarrow \mathfrak{b}$$

where

each t_i ← c_i is a single *T*-assignment
 (a term and a *T*-value of matching sorts)
 I ← b is a single Boolean assignment
 (a term of eart Back and a truth value)

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 - (a term and a \mathcal{T} -value of matching sorts)
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- Soundness requirement:

Every model of the premisses is a model of the conclusion

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Example: $(x \leftarrow \sqrt{2}), (y \leftarrow \sqrt{2}) \vdash x \cdot y \simeq 2$ (evaluation inference)

What is a theory module?

A set of inferences of the form

$$t_1 \leftarrow \mathfrak{c}_1, \ldots, t_k \leftarrow \mathfrak{c}_k \vdash I \leftarrow \mathfrak{b}$$

where

• each
$$t_i \leftarrow \mathfrak{c}_i$$
 is a single \mathcal{T} -assignment

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Soundness requirement:

Every model of the premisses is a model of the conclusion i.e. any \mathcal{T}^+ -model of $t_1 \simeq \mathfrak{c}_1 \land \ldots \land t_k \simeq \mathfrak{c}_k^*$ is a model of $l \simeq \mathfrak{b}$

Example: $(x \leftarrow \sqrt{2}), (y \leftarrow \sqrt{2}) \vdash x \cdot y \simeq 2$ (evaluation inference)

*that interprets distinct constants within $\mathfrak{c}_1, \ldots, \mathfrak{c}_k$ by distinct elements

What is a theory module? (Equality inferences)

All theory modules have the equality inferences:

 $t_1 \leftarrow \mathfrak{c}_1, t_2 \leftarrow \mathfrak{c}_2 \vdash t_1 \simeq t_2$ if \mathfrak{c}_1 and \mathfrak{c}_2 are the same value $t_1 \leftarrow \mathfrak{c}_1, t_2 \leftarrow \mathfrak{c}_2 \vdash t_1 \not\simeq t_2$ if \mathfrak{c}_1 and \mathfrak{c}_2 are distinct values

$$ert egin{array}{ccc} ert & t_1\simeq t_1\\ t_1\simeq t_2dash & t_2\simeq t_1\\ t_1\simeq t_2, t_2\simeq t_3ert & t_1\simeq t_3 \end{array}$$

Trail

... is a stack of justified assignments $_{H\vdash}(t\leftarrow \mathfrak{c})$ and decisions $_?(t\leftarrow \mathfrak{c})$ Justification H: a set of assignments that appear earlier on the trail Trail initialised with input problem

(assignments with empty justifications).

Example (trail grows downwards):

(*I*←true) abbreviated as *I*

trail items	just.	
$-2 \cdot x - y < 0$	{}	
x + y < 0	{}	
x < -1	{}	
<i>y</i> ←0	?	
-y < -2	$\{0,2\}$	
	$\begin{aligned} -2 \cdot x - y < 0 \\ x + y < 0 \\ x < -1 \\ y \leftarrow 0 \end{aligned}$	$ \begin{array}{c} -2 \cdot x - y < 0 \{\} \\ x + y < 0 \{\} \\ x < -1 \{\} \\ y \leftarrow 0 ? \end{array} $

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Example (trail grows downwards):

($l \leftarrow true$) abbreviated as l

Level: greatest decision involved

id	trail items	just.	lev.
0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0
2	x < -1	{}	0
3	<i>y</i> ←0	?	1
4	-y < -2	{0,2}	0

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Example (trail grows downwards):

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Level: greatest decision involved

Here: conflict of level 1 (if conflict is of level 0... ... problem is unsat)

id	trail items	just.	lev.
0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0
2	x < -1	{}	0
3	y←0	?	1
4	-y < -2	{0,2}	0

Let ${\mathcal T}$ be a theory with a specific ${\mathcal T}\text{-module}.$

 $\begin{array}{rcl} \mathsf{Decide} & \\ \Gamma & \longrightarrow & \Gamma, {}_?(t \leftarrow \mathfrak{c}) \end{array}$

Deduce

$$\begin{array}{rcl} \Gamma & \longrightarrow & \Gamma, _{J\vdash}(t{\leftarrow}\mathfrak{b}) & \quad \text{if } J\vdash_{\mathcal{T}} (t{\leftarrow}\mathfrak{b}) \text{ and } J\subseteq \Gamma, \\ & \quad \text{and } t{\leftarrow}\overline{\mathfrak{b}} \text{ is not in } \Gamma, \end{array}$$

Conflict

$$\begin{array}{rcl} \Gamma & \longrightarrow & \langle \Gamma; J, (t \leftarrow \overline{\mathfrak{b}}) \rangle & \text{if } J \vdash_{\mathcal{T}} (t \leftarrow \mathfrak{b}) \text{ and } J \subseteq \Gamma, \\ & \text{and } t \leftarrow \overline{\mathfrak{b}} \text{ is in } \Gamma \end{array}$$

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Conflict

$$\begin{array}{ccc}
 \Gamma &\longrightarrow & \langle \Gamma; J, (t \leftarrow \overline{\mathfrak{b}}) \rangle & \text{if } J \vdash_{\mathcal{T}} (t \leftarrow \mathfrak{b}) \text{ and } J \subseteq \Gamma, \\
 & \text{and } t \leftarrow \overline{\mathfrak{b}} \text{ is in } \Gamma
 \end{array}$$

Conflict states $\langle \Gamma; E \rangle$ (*E* conflicting set of assignments from Γ) are subject to conflict-solving rules similar to MCSAT and CDCL, like resolve:

 $\langle \Gamma; \underline{E}, (\underline{t} {\leftarrow} \mathfrak{c}) \rangle \longrightarrow \langle \Gamma; \underline{E} \cup \underline{H} \rangle \quad \text{if }_{\underline{H} \vdash} (\underline{t} {\leftarrow} \mathfrak{c}) \text{ is in } \Gamma \text{ and} \dots$

Let ${\mathcal T}$ be a theory with a specific ${\mathcal T}\text{-module}.$

 $\begin{array}{rcl} \text{Decide} \\ \Gamma & \longrightarrow & \Gamma, \gamma(t \leftarrow \mathfrak{c}) \end{array}$

Deduce

$$\label{eq:Gamma-formula} \begin{array}{rcl} \Gamma & \longrightarrow & \Gamma, \ _{J\vdash}(t{\leftarrow}\mathfrak{b}) & \text{ if } J \vdash_{\mathcal{T}} (t{\leftarrow}\mathfrak{b}) \mbox{ and } J \subseteq \Gamma, \\ & \mbox{ and } t{\leftarrow}\overline{\mathfrak{b}} \mbox{ is not in } \Gamma, \\ & \mbox{ and } t \mbox{ is in } \mathcal{B} \end{array}$$

Conflict

$$\ \ \longrightarrow \ \ \langle \Gamma; J, (t \leftarrow \overline{\mathfrak{b}}) \rangle \quad \text{if } J \vdash_{\mathcal{T}} (t \leftarrow \mathfrak{b}) \text{ and } J \subseteq \Gamma, \\ \text{ and } t \leftarrow \overline{\mathfrak{b}} \text{ is in } \Gamma$$

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CDSAT is parameterized by finite set of terms \mathcal{B} called global basis. Let \mathcal{T} be a theory with a specific \mathcal{T} -module.

Decide

 $\Gamma \longrightarrow \Gamma_{?}(t \leftarrow \mathfrak{c})$

Deduce

$$\begin{array}{ccc} \Gamma & \longrightarrow & \Gamma, _{J\vdash}(t {\leftarrow} \mathfrak{b}) & \text{ if } J \vdash_{\mathcal{T}} (t {\leftarrow} \mathfrak{b}) \text{ and } J \subseteq \Gamma, \\ & \text{ and } t {\leftarrow} \overline{\mathfrak{b}} \text{ is not in } \Gamma, \\ & \text{ and } t \text{ is in } \mathcal{B} \end{array}$$

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 $\begin{array}{rcl} \Gamma & \longrightarrow & \Gamma, _?(t {\leftarrow} \mathfrak{c}) & \quad \text{if } t {\leftarrow} \mathfrak{c} \text{ is "relevant \& acceptable"} \\ & \quad \text{given } \mathcal{T} \text{'s view of the trail } \Gamma \end{array}$

Deduce

$$\begin{array}{ccc} \Gamma & \longrightarrow & \Gamma, _{J\vdash}(t {\leftarrow} \mathfrak{b}) & \text{ if } J \vdash_{\mathcal{T}} (t {\leftarrow} \mathfrak{b}) \text{ and } J \subseteq \Gamma, \\ & \text{ and } t {\leftarrow} \overline{\mathfrak{b}} \text{ is not in } \Gamma, \\ & \text{ and } t \text{ is in } \mathcal{B} \end{array}$$

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$$f(a[i:=v][j]) \simeq w$$
, $w-2 \simeq f(u)$, $i \simeq j$, $u \simeq v$

id	trail items	just.	lev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0

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2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	u←c	?	1

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1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	u←¢	?	1
5	v←c	?	2

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id	trail items	just.	lev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	u←¢	?	1
5	v←c	?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3

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4	u←¢	?	1
5	v←¢	?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	<i>w</i> ←0	?	4

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4	u←¢	?	1
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7	<i>w</i> ←0	?	4
8	$f(a[i:=v][j]) \leftarrow 0$?	5

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7	<i>w</i> ←0	?	4
8	$f(a[i:=v][j]) \leftarrow 0$?	5
9	$f(u) \leftarrow -2$?	6

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1	$w-2 \simeq f(u)$	{}	0
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3	$u \simeq v$	{}	0
4	u←¢	?	1
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6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	<i>w</i> ←0	?	4
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9	$f(u) \leftarrow -2$?	6
10	$u \simeq a[i:=v][j]$	$\{4,6\}$	3

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4	u←c	?	1
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6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	<i>w</i> ←0	?	4
8	$f(a[i:=v][j]) \leftarrow 0$?	5
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10	$u \simeq a[i:=v][j]$	$\{4, 6\}$	3
11	$f(u) \not\simeq f(a[i:=v][j])$	{8,9}	6

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3	$u \simeq v$	{}	0
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9	$f(u) \leftarrow -2$?	6
10	$\mathbf{u} \simeq \mathbf{a}[\mathbf{i}:= \mathbf{v}][\mathbf{j}]$	{4,6}	3
11	$f(\mathbf{u}) \not\simeq f(\mathbf{a}[\mathbf{i}:=\mathbf{v}][\mathbf{j}])$	8,9	6
conflict E^1 : {10, 11}			6

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0	$f(a[i:=v][j]) \simeq w$	{}	0	0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0	1	$w-2 \simeq f(u)$	{}	0
2	$i\simeq j$	{}	0	2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0	3	$u \simeq v$	{}	0
4	u←¢	?	1	4	$u \leftarrow \mathfrak{c}$?	1
5	v←c	?	2	5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3	6	$a[i:=v][j] {\leftarrow} \mathfrak{c}$?	3
7	<i>w</i> ←0	?	4	7	$u \simeq a[i:=v][j]$	{4,6}	3
8	$f(a[i:=v][j]) \leftarrow 0$?	5	8	$f(u) \simeq f(a[i:=v][j])$	{7}	3
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11	$f(\mathbf{u}) \not\simeq f(\mathbf{a}[\mathbf{i}:=\mathbf{v}][\mathbf{j}])$	{8,9}	6				
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1	$w-2 \simeq f(u)$	{}	0	1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0	2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0	3	$u \simeq v$	{}	0
4	u←¢	?	1	4	$u \leftarrow \mathfrak{c}$?	1
5	v←c	?	2	5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3	6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	<i>w</i> ←0	?	4	7	$u \simeq a[i:=v][j]$	$\{4, 6\}$	3
8	$f(a[i:=v][j]) \leftarrow 0$?	5	8	$f(u) \simeq f(a[i:=v][j])$	{7}	3
9	$f(u) \leftarrow -2$?	6				
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11	$f(\mathbf{u}) \simeq f(\mathbf{a}[\mathbf{i}:=\mathbf{v}][\mathbf{j}])$	{8,9}	6				
conflict E^1 : {10, 11}		6					

3. Termination, Soundness and Completeness

Termination:

Theorem: If the global basis \mathcal{B} is finite, CDSAT terminates.

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For each theory module ${\mathcal T}$ involved,

and all finite sets X of terms (think of it as the terms of the input), we must have a finite set of terms $basis_{\mathcal{T}}(X)$, called local basis

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(those terms possibly introduced by ${\mathcal T}$ during the run)

If the local bases of $\mathcal{T}_1, \ldots, \mathcal{T}_n$ satisfy some (collective) properties, then it is possible to define a finite global basis \mathcal{B} for $\bigcup_{k=1}^n \mathcal{T}_k$.

Termination:

Theorem: If the global basis $\ensuremath{\mathcal{B}}$ is finite, CDSAT terminates.

How to determine $\mathcal{B}?$ It should be sufficiently large to allow each theory module to explain its conflicts via deductions.

For each theory module ${\mathcal T}$ involved,

and all finite sets X of terms (think of it as the terms of the input), we must have a finite set of terms $basis_{\mathcal{T}}(X)$, called local basis

(those terms possibly introduced by \mathcal{T} during the run)

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Soundness:

Theorem: Since each theory module ${\cal T}$ is made of sound inferences, if the calculus ends with a conflict of level 0,

then the input was unsat.

(you can even get a proof)

Do we have a model?

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This relies on a completeness condition for theory modules:

- A \mathcal{T} -module is complete if for any Γ ,
 - Either There exists a \mathcal{T}^+ -model of the theory view of Γ
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If CDSAT cannot make any further transitions, then the trail describes a model for the union of the (extended) theories.

Theory modules given as examples in the paper ► EUF

 $(t_i \simeq u_i)_{i=1...n}, (f(t_1, \ldots, t_n) \not\simeq f(u_1, \ldots, u_n)) \vdash_{\mathsf{EUF}} \quad \bot$

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- Black box procedure for equality-sharing: coarse-grain inferences

 $I_1 \leftarrow \mathfrak{b}_1, \ldots, I_n \leftarrow \mathfrak{b}_n \vdash_{\mathcal{T}} \bot$

where l_1, \ldots, l_n are formulæ, and the conjunction of the literals corresponding to the Boolean assignments $l_1 \leftarrow b_1, \ldots, l_n \leftarrow b_n$ is \mathcal{T} -unsatisfiable (as detected by the black box)

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Arrays: similar, except for extensionality

 $(\mathcal{T}_0\text{-complete for all }\mathcal{T}_0 \text{ such that...})$

 LRA: evaluation inference, Fourier-Motzkin resolution inference as in MCSAT, etc

(\mathcal{T}_0 -complete for all \mathcal{T}_0 imposing |Q| infinite)

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where l_1, \ldots, l_n are formulæ, and the conjunction of the literals corresponding to the Boolean assignments $l_1 \leftarrow b_1, \ldots, l_n \leftarrow b_n$ is \mathcal{T} -unsatisfiable (as detected by the black box) (\mathcal{T}_0 -complete for all \mathcal{T}_0 imposing the cardinality of all known sorts but Bool to be countably infinite)

Concluding remarks

Learning:

Not needed for soundness, completeness, and termination, but highly desirable - in the paper's long version

- Proof production: is easy, each theory inference can come with a proof object, CDSAT only aggregates them in simple ways
- CDSAT is a framework: leaves large freedom to the design of search plans / strategies
- First-order assignments: I mostly presented them as a way to build a model of an input formula - they could be part of the input

$$l_1 \leftarrow \mathfrak{b}_1, \ldots, l_k \leftarrow \mathfrak{b}_k, t_1 \leftarrow \mathfrak{c}_1, \ldots, t_j \leftarrow \mathfrak{c}_j$$

The question is then "Is there a model of the constraints (in sort Bool) that extends these first-order assignments?" Note: the choice of theory extensions impacts the meaning of the question.

We suggest to call this SMA,

for Satisfiability Modulo Assignments.

 State of the implementation: An OCaml prototype implements the CDSAT framework (with learning), with theory module Bool

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An example in Linear Rational Arithmetic $l_0: (-2 \cdot x - y < 0), \qquad l_1: (x + y < 0), \qquad l_2: (x < -1)$

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 l₃ and l₄ give clash of bounds for y

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Trail = stack of justified assignments $_{H\vdash}(t\leftarrow \mathfrak{c})$ and decisions $_{?}(t\leftarrow \mathfrak{c})$, Trail initialised with input problem (assign. with empty justifications)

($l \leftarrow true$) abbrev. as l

id	trail items	just.	
0	$-2 \cdot x - y < 0$	{}	
1	x + y < 0	{}	
2	x < -1	{}	

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($l \leftarrow$ true) abbrev. as l	id	trail items	just.	lev.
	0	$-2 \cdot x - y < 0$	{}	0
Level:	1	x + y < 0	{}	0
greatest decision involved	2	x < -1	{}	0
	3	<i>y</i> ←0	?	1

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id	trail items	just.	lev.
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4	-y < -2	$\{0,2\}$	0

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Level: greatest decision involved

If conflict is of level 0... ...problem is unsat

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1	x + y < 0	{}	0
2	x < -1	{}	0
3	y ← 0	?	1
4	-y < -2	$\{0, 2\}$	0
	conflict E^1 : {3	8,4}	1

	Phase	2	
id	trail items	just.	lev.
0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0
2	x < -1	{}	0
3	-y < -2	$\{0, 2\}$	0

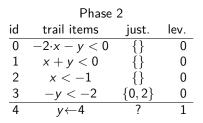
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id	trail items	just.	lev.
0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0
2	x < -1	{}	0
3	-y < -2	$\{0,2\}$	0
4	<i>y</i> ←4	?	1
5	<i>y</i> < 0	$\{0,1\}$	0

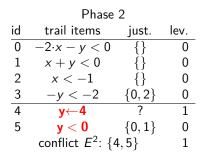
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id	trail items	just.	lev.	
0	$-2 \cdot x - y < 0$	{}	0	
1	x + y < 0	{}	0	
2	x < -1	{}	0	
3	y ← 0	?	1	
4	-y < -2	$\{0, 2\}$	0	
	conflict E^1 : {3	8,4}	1	

Phase 3				
id	trail items	just.	lev.	
0	$-2 \cdot x - y < 0$	{}	0	
1	x + y < 0	{}	0	
2	x < -1	{}	0	
3	-y < -2	$\{0, 2\}$	0	
4	<i>y</i> < 0	$\{0, 1\}$	0	

Trail = stack of justified assignments $_{H\vdash}(t\leftarrow \mathfrak{c})$ and decisions $_{?}(t\leftarrow \mathfrak{c})$, Trail initialised with input problem (assign. with empty justifications)

($l \leftarrow true$) abbrev. as l

Level: greatest decision involved

If conflict is of level 0... ... problem is unsat

Phase 1					
id	trail items	just.	lev.		
0	$-2 \cdot x - y < 0$	{}	0		
1	x + y < 0	{}	0		
2	x < -1	{}	0		
3	y ← 0	?	1		
4	-y < -2	$\{0, 2\}$	0		
conflict E^1 : {3, 4}		1			

Phase 2					
id	trail items	just.	lev.	id	
0	$-2 \cdot x - y < 0$	{}	0	0	
1	x + y < 0	{}	0	1	
2	x < -1	{}	0	2	
3	-y < -2	$\{0,2\}$	0	3	
4	y←4	?	1	4	
5	$\mathbf{y} < 0$	$\{0,1\}$	0	5	
	conflict E^2 : {4	1,5}	1		

Phase 3					
id	trail items	just.	lev.		
0	$-2 \cdot x - y < 0$	{}	0		
1	x + y < 0	{}	0		
2	x < -1	{}	0		
3	-y < -2	$\{0, 2\}$	0		
4	<i>y</i> < 0	$\{0,1\}$	0		
5	0 < -2	{3,4}	0		

Trail

Trail = stack of justified assignments $_{H\vdash}(t\leftarrow \mathfrak{c})$ and decisions $_{?}(t\leftarrow \mathfrak{c})$, Trail initialised with input problem (assign. with empty justifications)

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Phase 1			
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0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0
2	x < -1	{}	0
3	y ← 0	?	1
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	conflict E^1 : {3	8,4}	1

Phase 2			Phase 3				
id	trail items	just.	lev.	id	trail items	just.	lev.
0	$-2 \cdot x - y < 0$	{}	0	0	$-2 \cdot x - y < 0$	{}	0
1	x + y < 0	{}	0	1	x + y < 0	{}	0
2	x < -1	{}	0	2	x < -1	{}	0
3	-y < -2	$\{0, 2\}$	0	3	-y < -2	$\{0, 2\}$	0
4	y←4	?	1	4	<i>y</i> < 0	$\{0,1\}$	0
5	$\mathbf{y} < 0$	$\{0, 1\}$	0	5	0 < −2	{3,4}	0
	conflict E^2 : {4	1,5}	1		conflict E ³ : {	[5]	0

CDSAT: Search rules

Parameterized by finite set of terms \mathcal{B} called global basis Let \mathcal{T} be a theory with a specific \mathcal{T} -module.

Decide

$$\Gamma \longrightarrow \Gamma, {}_{?}(t \leftarrow c)$$
 if $t \leftarrow c$ (in \mathcal{T} -public sort) does not
immediately violate \mathcal{T} 's view of the trail $\Gamma_{\mathcal{T}}$
Deduce
 $\Gamma \longrightarrow \Gamma, {}_{J\vdash L}$ if $J \vdash_{\mathcal{T}} L$ and $J \subseteq \Gamma$,
and \overline{L} is not in Γ ,
and L is for a formula in \mathcal{B}
Conflict
 $\Gamma \longrightarrow \langle \Gamma; J, \overline{L} \rangle$ if $J \vdash_{\mathcal{T}} L$ and $J \subseteq \Gamma$,
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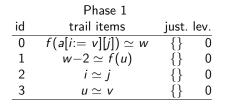
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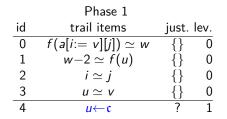
CDSAT: Conflict analysis rules

Fail
$$\langle \Gamma; \emptyset \rangle \longrightarrow$$
 unsatUndo
 $\langle \Gamma; E, A \rangle \longrightarrow \Gamma^{\leq m-1}$ if A is a non-Boolean decision
of level $m > \text{level}_{\Gamma}(E)$ Backjump
 $\langle \Gamma; E, L \rangle \longrightarrow \Gamma^{\leq m}, E \vdash \overline{L}$ if $\text{level}_{\Gamma}(L) > m$, where $m = \text{level}_{\Gamma}(E)$ Resolve
 $\langle \Gamma; E, A \rangle \longrightarrow \langle \Gamma; E \cup H \rangle$ if $_{H \vdash} A$ is in Γ and
 H does not contain a non-Boolean decision
whose level is $\text{level}_{\Gamma}(E, A)$ UndoDecide
 $\langle \Gamma; E, L, L' \rangle \longrightarrow \Gamma^{\leq m-1}, ?\overline{L}$ if $_{H \vdash} L$ and $_{H' \vdash} L'$ are in Γ and
 $H \cap H'$ contains a non-Boolean decision
of level $m = \text{level}_{\Gamma}(E, L, L')$

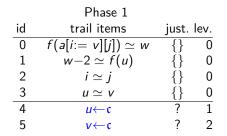
$$f(a[i:=v][j]) \simeq w$$
, $w-2 \simeq f(u)$, $i \simeq j$, $u \simeq v$



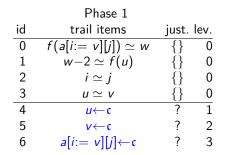
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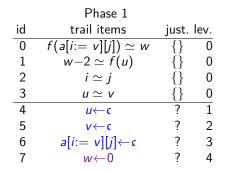
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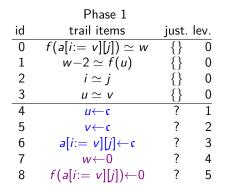
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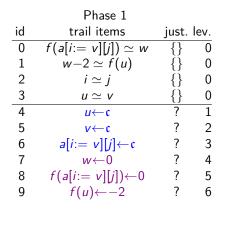
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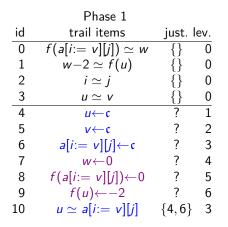
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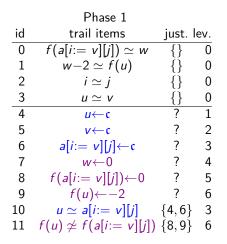
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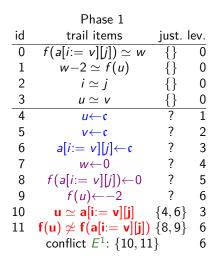
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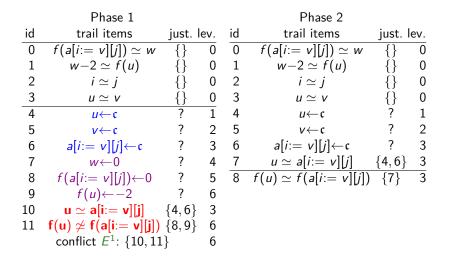
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	Phase 2		
id	trail items	just.	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	$u\simeq a[i:=v][j]$	$\{4,6\}$	3
8	$f(u) \simeq f(a[i:=v][j])$	{7}	3

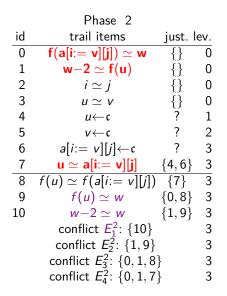
	Phase 2		
id	trail items	just. l	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j]{\leftarrow}\mathfrak{c}$?	3
7	$u \simeq a[i:=v][j]$	$\{4, 6\}$	3
8	$f(u) \simeq f(a[i:=v][j])$	{7}	3
9	$f(u) \simeq w$	$\{0,8\}$	3

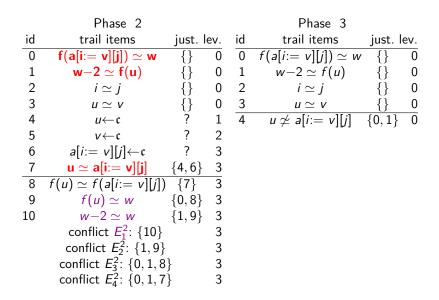
	Phase 2		
id	trail items	just. l	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
5	$v \leftarrow \mathfrak{c}$?	2
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8	$f(u) \simeq f(a[i:=v][j])$	{7}	3
9	$f(u) \simeq w$	$\{0, 8\}$	3
10	$w-2 \simeq w$	$\{1, 9\}$	3

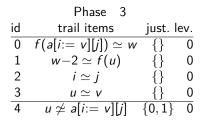
	Phase 2		
id	trail items	just. I	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
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10	${\sf w-2}\simeq {\sf w}$	$\{1, 9\}$	3
	conflict E_1^2 : {10}	-	3

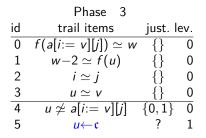
	Phase 2		
id	trail items	just. I	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	$u \simeq a[i:=v][j]$	$\{4, 6\}$	3
8	$f(u) \simeq f(a[i:=v][j])$	{7}	3
9	${f f}({f u})\simeq {f w}$	$\{0, 8\}$	3
10	$w-2 \simeq w$	$\{1, 9\}$	3
	conflict E_1^2 : {10}		3
	conflict E_2^2 : {1,9}		3

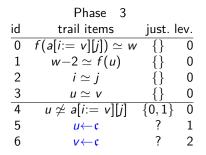
	Phase 2		
id	trail items	just. le	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	${\sf w}{-}{\sf 2}\simeq{\sf f}({\sf u})$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \leftarrow \mathfrak{c}$?	1
5	$v \leftarrow \mathfrak{c}$?	2
6	$a[i:=v][j] \leftarrow \mathfrak{c}$?	3
7	$u\simeq a[i:=v][j]$	$\{4, 6\}$	3
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10	$w-2 \simeq w$	$\{1, 9\}$	3
	conflict E_1^2 : {10}		3
	conflict E_2^2 : {1,9}		3
	conflict E_3^2 : {0, 1, 8	}	3







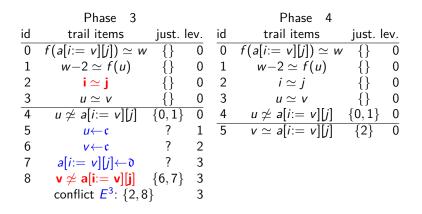


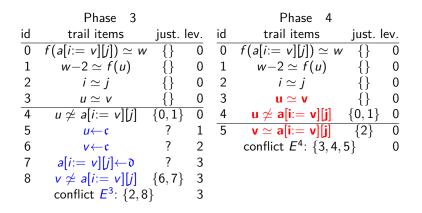


	Phase 3		
id	trail items	just. l	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i\simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \not\simeq a[i:=v][j]$	$\{0, 1\}$	0
5	u←¢	?	1
6	v←¢	?	2
7	$a[i:=v][j]{\leftarrow}\mathfrak{d}$?	3

	Phase 3		
id	trail items	just. I	ev.
0	$f(a[i:=v][j]) \simeq w$	{}	0
1	$w-2 \simeq f(u)$	{}	0
2	$i \simeq j$	{}	0
3	$u \simeq v$	{}	0
4	$u \not\simeq a[i:=v][j]$	$\{0, 1\}$	0
5	u←c	?	1
6	v←¢	?	2
7	$a[i:=v][j] \leftarrow \mathfrak{d}$?	3
8	v eq a[i:=v][j]	$\{6,7\}$	3

Phase 3
id trail items just. lev.
0
$$f(a[i:=v][j]) \simeq w$$
 {} 0
1 $w-2 \simeq f(u)$ {} 0
2 $i \simeq j$ {} 0
3 $u \simeq v$ {} 0
4 $u \not\simeq a[i:=v][j]$ {0,1} 0
5 $u \leftarrow c$? 1
6 $v \leftarrow c$? 2
7 $a[i:=v][j] \leftarrow 0$? 3
8 $v \not\simeq a[i:=v][j]$ {6,7} 3
conflict E^3 : {2,8} 3





LRA-public sorts: just Q.

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Evaluations:

$$t_1 \leftarrow q_1, \ldots, t_n \leftarrow q_n \vdash_{\mathsf{LRA}} I \leftarrow b$$

where I evaluates to b under the assignments

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Fourier-Motzkin resolutions:

$$(e_1 \lessdot_1 x), (x \lessdot_2 e_2) \vdash_{\mathsf{LRA}} (e_1 \lessdot_3 e_2)$$

where \lt is < or \le ... (triggered only where e_1 and e_2 have been assigned values)

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(triggered only where e_1 and e_2 have been assigned values)

Treatment of disequality:

$$(e_1 \leq x), (x \leq e_2), (e_1 \simeq e_0), (e_2 \simeq e_0), (x \not\simeq e_0) \vdash_{\mathsf{LRA}} \bot$$

(triggered only where e_0 , e_1 and e_2 have been assigned values)