

Sensor Coordination using Active Dataspaces

Steven Cheung

NSF NOSS PI Meeting
October 18, 2004



Outline

- Motivation/Problem
 - Characteristics of sensor networks
 - Techniques for building sensor network applications
 - Why sensor network programming hard?
 - Need: High-level programming abstraction
- Our approach
 - Active dataspace (ADS)
 - Features of ADS
 - Tuples on demand
- Example scenario
 - Vehicle detection: Setup
 - Event sequence: Bootstrapping
 - Event sequence: Detection phase

Characteristics of sensor networks

- Resource constraints
 - Energy reserve
 - Computation power
 - Memory
- Unpredictable communication links
 - Intermittent connectivity
 - Asymmetric links and radio directionality
- Node failure
 - Exposed to harsh environment and attacks
 - Battery depletion
- Possibly large number of nodes
- Possibly difficult deployment environment

Techniques for building sensor network applications

- General resource conservation
 - In-network processing
 - Localized algorithms
 - Hibernation (e.g., sentry service)
- Optimizations for key communication patterns
 - Tree-based aggregation scheme (many-1)
 - Firecracker protocol (1-many)
- Adaptive protocols
 - Protocols that adaptively optimize communication based on local information and feedback (e.g., directed diffusion and PARC's CB-LRTA*)
- Exploiting redundancy and broadcast medium

Why sensor network programming hard?



Deploying new or additional sensors

Limited CPU power and memory

Scalability

Locality

Sensor nodes

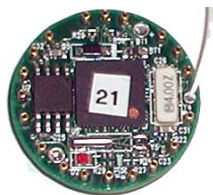
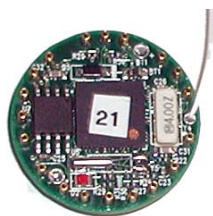
Applications

Intermittent end-to-end connectivity

Hibernation

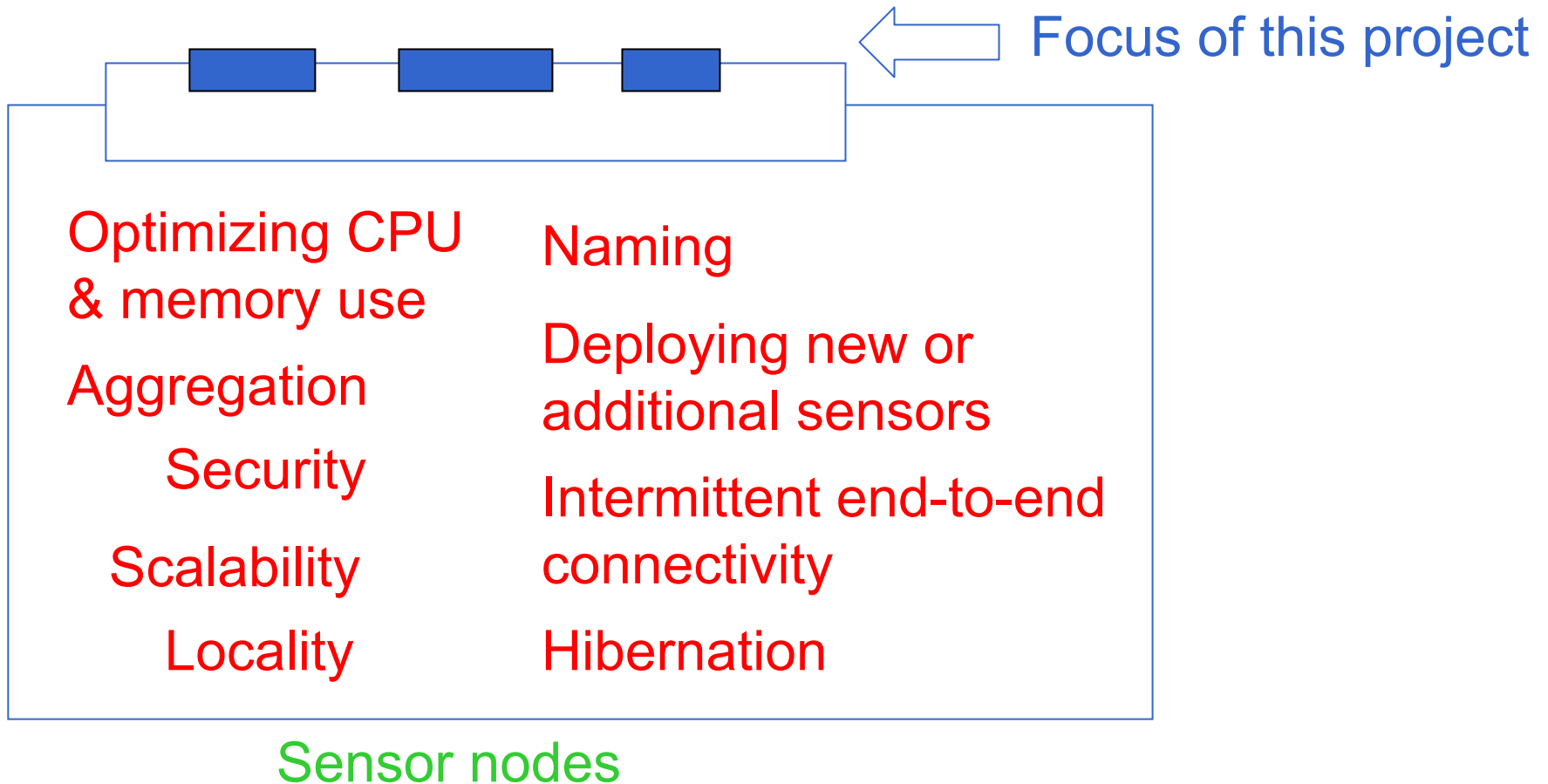
Attacks

Data aggregation



Need: High-level programming abstraction

Applications



Active dataspace (ADS)

- ADS is an active data repository that provides associative operations for data access
- Inspired by the tuple space model [Gelernter 85], developed for parallel computing
- Every data tuple (or record) contains a list of fields
- Basic TS operations:
 - *in* is used to remove tuples from TS
 - *rd* to read tuples
 - *out* to create data tuples
 - *eval* to create “active” tuples

Features of ADS

- Data-centric model
- Time-uncoupling: Data consumers and producers do not need to be active at the same time
- Identity-uncoupling: Endpoints do not need to know each other's identities
- Stable network paths between endpoints need not exist
- *Virtual tuples* support data generation on demand
- Tuple set operator and *cardinality constraint* to facilitate in-network aggregation
- *Search constraint* for specifying the scope and preferences for tuple selection to exploit locality

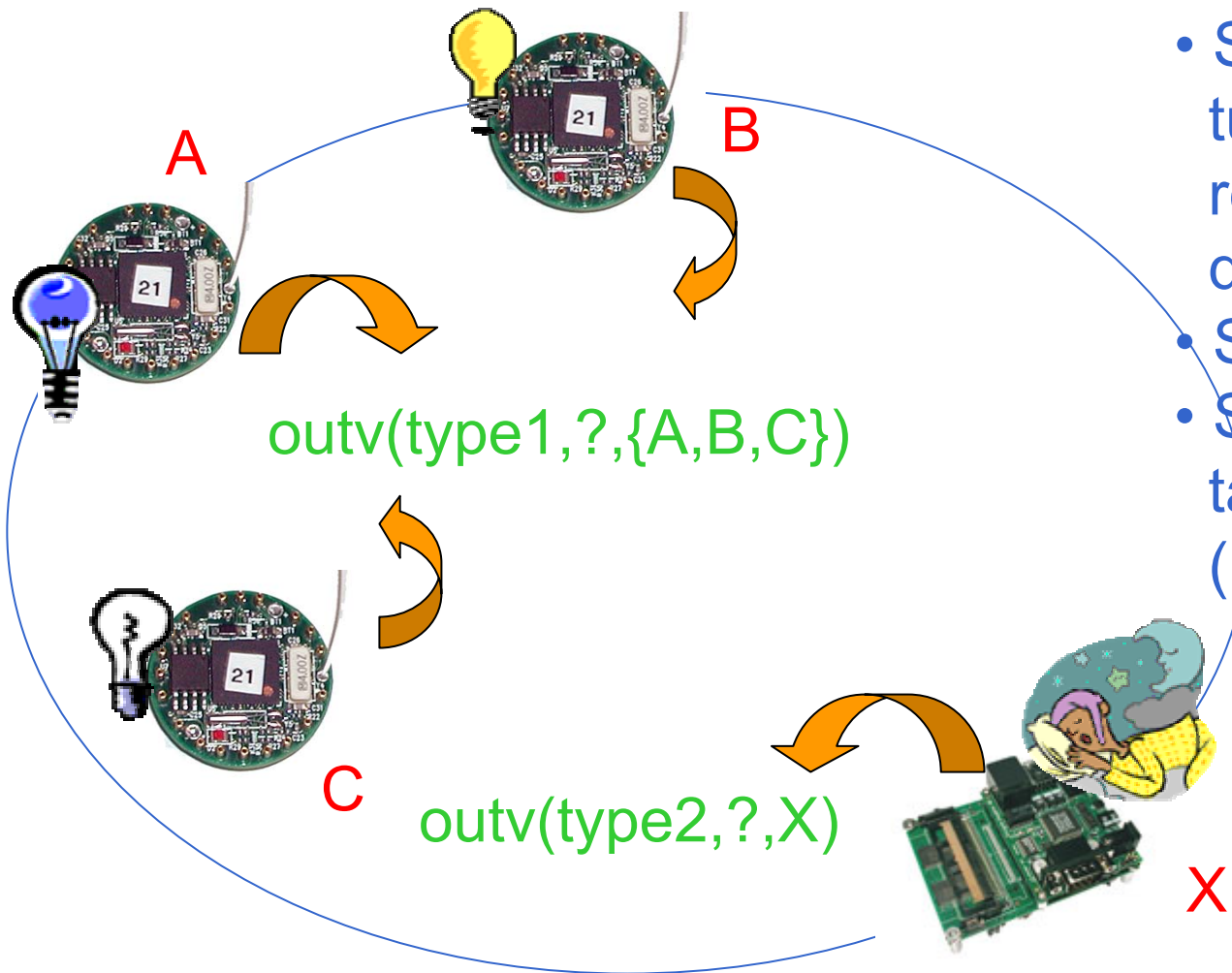
Tuples on demand

- Motivation: To enable sensor nodes to conserve energy and other resources during time intervals in which their work is not needed
- A virtual tuple represents the capability of a node to generate a certain type of tuple specified by the virtual tuple
- When a tuple request matches a virtual tuple, the corresponding node will be contacted to produce the data on demand
- Use of virtual tuple is transparent to data consumers

Vehicle detection: Setup

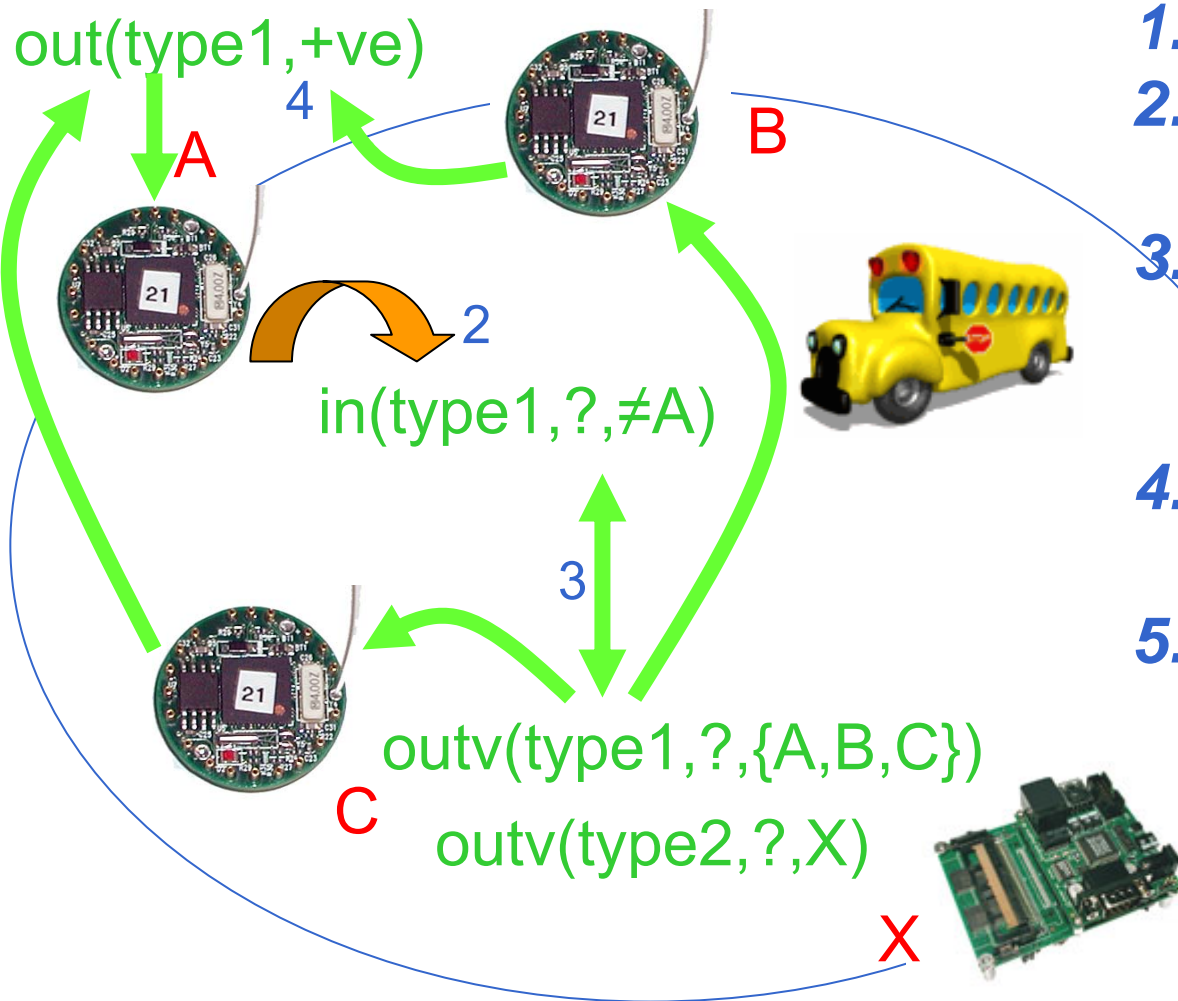
- Sensors deployed in a region for vehicle detection
- 2 types of sensor nodes
- Type 1 (Sensors A, B, and C) :
 - Low-cost to operate
 - less accurate
 - has a shorter range
 - cannot classify vehicles
- Type 2 (Sensor X):
 - Expensive to use
 - more accurate
 - have a longer range
 - can distinguish different classes of vehicles

Event sequence: Bootstrapping



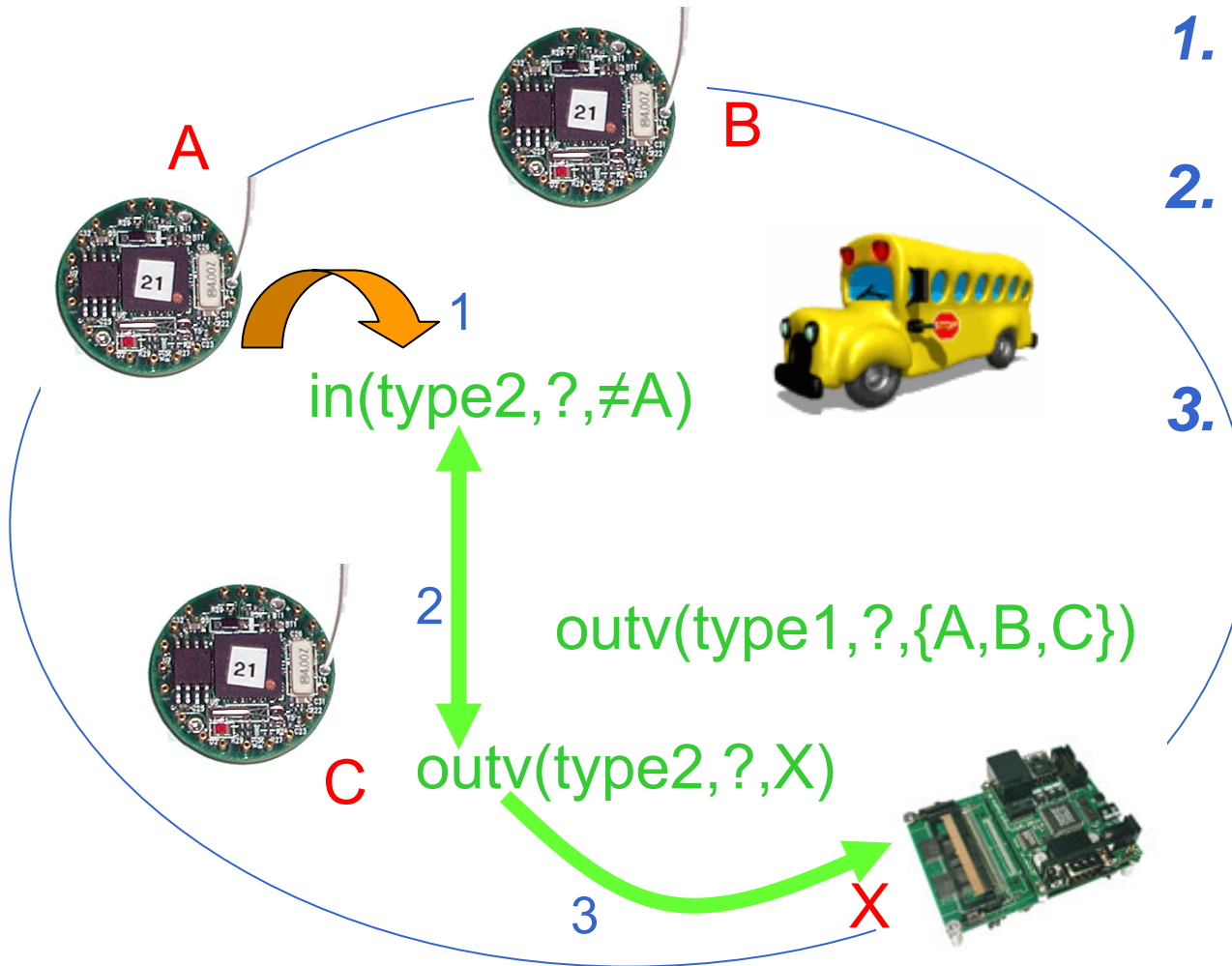
- Sensors put virtual tuples in ADS, which represent their detection capabilities
- Sensor **X** hibernates
- Sensors **A**, **B**, & **C** take turn being active (i.e., the sentry)

Event sequence: Detection phase (1)



1. *A* detects a vehicle
2. *A* requests other type1 sensor data
3. **ADS** matches the request with *B*'s and *C*'s virtual tuples
4. *B* and *C* produce sensor reading tuples
5. *A* confirms detection with *B*'s and *C*'s input

Event sequence: Detection phase (2)



1. *A* requests type2 sensor data
2. **ADS** matches the request with *X*'s virtual tuple
3. *X* is awoken for vehicle detection

Expected results

- High-level programming model and language to ease sensor network programming for a wide range of application domains
- Architecture and techniques to implement a resource-efficient, adaptive, and trustworthy ADS system