## Rewriting in Practice

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## Systems Biology

Enormous amounts of data being generated

- DNA sequencing: Fully sequencing genomes is rapid and easy
- DNA microarray: Which genes are being transcribed
- Proteomics: Which proteins are present
- Flow cytometry: Concentration in individual cells

And how to use it to predict clinical observations and phenotypes?

## Systems Biology

Model-based development
Also, a common feature in embedded system design
Goal: Models can help

- perform in-silico experiments
- guide wet lab experiments
- suggest novel drug targets


## Nutrient Sets

Goal: Starting from the genome, find nutrient sets on which that organism will grow

- Sequence genome of the organism
- Extract genes
- Predict metabolic network
- Predict growth on nutrient sets


## Metabolic Network: Rewriting-based Modeling

Rewriting is used as a language for writing Petrinets
Petrinets: Ground AC rewrite systems with 1 AC symbol
Example:

$$
\begin{array}{llll}
a_{1}: & & A+B & \rightarrow C+D \\
a_{2}: & & C+A & \rightarrow E
\end{array}
$$

The numeric parameters $a_{1}, a_{2}$ capture relative affinity/preference/ likelihood
Typical metabolic networks have 1000's of reactions and metabolites

## Rewrite Rules as Models

Rewrite rules used to model

- metabolic networks
- cell signaling
- gene regulatory networks

Terms can have complex structure: compartments, binding sites

Three different semantics of these rules

- stochastic
- deterministic
- nondeterministic


## Stochastic Firing: Chemical Master Equation

Strategy for firing rewrite rules: stochastic
Physics-based models of biochemical reaction networks: stochastic Petrinets
Semantics is given using the CME
$X: \quad$ set of metabolites, $|X|=n$; e.g. $X=\{A, B, C, D, E\}$
$R$ : set of reactions
$r: \quad$ a reaction, element of $\mathbb{N}^{n}$; e.g. $A+C \rightarrow E \mapsto[-1,0,-1,0,1]$
$P: \quad$ map from $N^{+^{n}} \times \mathbb{R}^{+} \mapsto[0,1]$

$$
\frac{d P(X, t)}{d t}=\sum_{r \in R} a(P(X-r, t), r)
$$

## Stochastic Firing: Example

$$
a_{1}: A+B \rightarrow C+D \quad a_{2}: \quad C+A \rightarrow E
$$

Evolving probability distribution:

|  | $\mathrm{A}=2, \mathrm{~B}=1, \mathrm{C}=\mathrm{D}=\mathrm{E}=0$ | $\mathrm{~A}=1, \mathrm{~B}=0, \mathrm{C}=1, \mathrm{D}=1, \mathrm{E}=0$ | $\mathrm{~A}=0, \mathrm{~B}=0, \mathrm{C}=0, \mathrm{D}=1, \mathrm{E}=1$ |
| :---: | :---: | :---: | :---: |
| 1 | 1 | 0 | 0 |
| 2 | $1 / 2$ | $1 / 2$ | 0 |
| 3 | $1 / 4$ | $1 / 2$ | $1 / 4$ |
| 4 | $1 / 8$ | $3 / 8$ | $1 / 2$ |
| 5 | $\ldots$ | $\ldots$ | $\ldots$ |
| 6 | 0 | 0 | 1 |

Difficulty: Not enough data to know how to compute $a$

## High-dimensional Markov Chain: Does not scale

## Deterministic Firing: Mass Action Dynamics

Approximation of CME using ordinary differential equations

$$
a_{1}: A+B \rightarrow C+D \quad a_{2}: \quad C+A \rightarrow E
$$

ODE model using mass action dynamics:

$$
\begin{aligned}
\frac{d A(t)}{d t} & =-a_{1} * A(t) * B(t)-a_{2} * A(t) * C(t) \\
\frac{d B(t)}{d t} & =-a_{1} * A(t) * B(t) \\
\frac{d C(t)}{d t} & =-a_{2} * A(t) * C(t)+a_{1} * A(t) * B(t) \\
\frac{d D(t)}{d t} & =a_{1} * A(t) * B(t) \\
\frac{d E(t)}{d t} & =a_{2} * A(t) * C(t)
\end{aligned}
$$

Issue: (i) approximate (ii) Still need $a_{1}, a_{2}$

## Nondeterministic Firing: Rewriting

Preferable because we do not need extra parameters
Organism grows if it can produce biomass compounds starting from nutrients
This is a reachability question
Petrinet reachability is decidable, but inefficient
Example: If $A, B$ are nutrients, and $E$ is a biomass compound, then:

$$
2 A+B \rightarrow A+C+D \quad \rightarrow \quad E+D
$$

## Reachability: Via Constraint Solving

We can perform approximate reachability via constraint solving
Example:

$$
A+B \rightarrow C+D \quad C+A \rightarrow E
$$

Constraints: Suppose initial state is $2 A+B$, we want to reach $D+E$

$$
\begin{array}{ll}
A: & -r_{1}-r_{2}+2=0 \\
B: & -r_{1}+1=0 \\
C: & r_{1}-r_{2}=0 \\
D: & r_{1}-1=0 \\
E: & r_{2}-1=0
\end{array}
$$

If $D+E$ is reachable from $2 A+B$, then above constraints are satisfiable This is called Flux Balance Analysis

## Nutrient Sets for E.Coli

We have used constraint solving for finding (minimal) nutrient sets for E.Coli
Flux Balance Analysis: an overapproximation of the reachability relation
We developed a constraint-based approach that captures reachability more accurately than FBA

Results:
(1) About $75 \%$ accuracy with experimental results
(2) Predicted growth of E.Coli on cynate as both Carbon and Nitrogen source, which was experimentally verified
(3) Can compute all minimal nutrient sets for E.Coli

## Rewriting in Biology

Apart from metabolic networks, rewrite rules are also commonly used for modeling signalling pathways

Signaling pathway: Biochemical reactions that show how signals are transmitted from the cell surface to the cell cytoplasm to nucleus

Questions of interest to biologists vary
visualization
reachability pathways
conflicts: $A \rightarrow^{*} C$ and $B \rightarrow^{*} D$, but $A+B-(A \cap B) \nrightarrow^{*} C+D$
knockouts: Is it possible $A \rightarrow{ }^{*} C$, but without using $B$
All analysis techniques should scale

## Competing Rules in EGF Stimulation Pathway



## Outline

Rewriting in

- Systems Biology
- Algorithm Description and Design
- Theorem Proving


## Algorithms

Rewriting is useful in two different ways in the study of algorithms:

- Rewriting-based descriptions for algorithms
- Rewriting as a paradigm for algorithm design


## Rewriting-based Descriptions

- Express the algorithmic problem by identifying the term structure of initial and final configuration
- Define an ordering on the space of configurations such that the final configuration is minimal
- Find local transition rules that decrease configuration measure


## Rewriting-based Descriptions

Such descriptions are obtained when writing algorithms in rewriting logic (such as, in Maude)

Example: Sorting can be described by

$$
X, a, Y, b, Z \quad \rightarrow \quad X, b, Y, a, Z \quad \text { if } a>b
$$

Benefit:

- Separates implementation from the algorithm
- Correctness argument simpler
- Algorithms are nondeterministic


## Algorithmic Design Paradigms

Some paradigms taught in a course on algorithms:

- greedy
- divide and conquer
- dynamic programming
- branch and bound

One important paradigm often not taught:

- completion


## Completion as Paradigm

## for Algorithm Design

- Express the algorithmic problem by identifying configurations as sets of facts
- Define an ordering on the facts and proofs
- Find local transition rules that add or delete facts such that
- proofs of (provable) facts do not get any bigger
- some proof gets smaller

In the final configuration, all facts have minimal proofs

## Completion-based Procedures: Examples

Shortest-path in a graph:
Deduce $\frac{C:=\left\{\ldots, \operatorname{path}\left(u, v, d_{u v}\right), \operatorname{path}\left(v, w, d_{v w}\right), \ldots\right\}}{C \cup\left\{\operatorname{path}\left(u, w, d_{u v}+d_{v w}\right)\right\}}$
Delete $\frac{C:=\left\{\ldots, \operatorname{path}(u, v, d), \operatorname{path}\left(u, v, d^{\prime}\right), \ldots\right\}}{C-\left\{\operatorname{path}\left(u, v, d^{\prime}\right)\right\}}$ if $d<d^{\prime}$

Orderings determine what deduction and deletion steps are acceptable
Deleted facts should have smaller proof using remaining facts
Deduced facts should make some proof smaller

## Benefits

- Uniform understanding of several algorithms
- Different orderings will yield different algorithms
- Strategy for applying the inference steps can be determined by other factors

Can optimize an algorithm by

- choosing an appropriate ordering
- choosing an appropriate strategy
- choosing an appropriate data structure


## Completion-based Algorithms

- Union-find
- Congruence closure
- Rational linear arithmetic (Simplex)
- Fourier-Motzkin
- Gröbner basis
- Ordered resolution

In this talk,

- Linear equalities
- Linear equalities + inequalities
- Nonlinear equalities
- Nonlinear equalities + inequalities


## Solving Linear Equations

Facts: $a_{1} x_{1}+\cdots+a_{n} x_{n}+b=0$
Pick an ordering $x_{1} \succ x_{2} \succ \cdots \succ x_{n}$
Define measure $m\left(a_{1} x_{1}+\cdots+a_{n} x_{n}+b=0\right):=\left\{x_{i} \mid a_{i} \neq 0\right\}$, and $m\left(x_{i}>0\right):=\left\{x_{i}\right\}$

Order facts by $\succ^{m}$ on their measures
Measure of a proof := measure of all facts used in it
Deduce $\frac{C:=\{\ldots, a x+Y=0, b x+Z=0, \ldots\}}{C \cup\{b Y-a Z=0\}}$

But, here, we need to do this even when $x$ is not maximal

## Solving Linear Arithmetic Equations

Get more flexibility in ordering facts
Distinguish: $a_{1} x_{1}+\cdots+a_{n} x_{n}+b=0$ and $a_{1} x_{1}=-a_{2} x_{2}-\cdots-a_{n} x_{n}-b$
Pick an ordering $x_{1} \succ x_{2} \succ \cdots \succ x_{n}$
Define measure $m\left(a_{1} x_{1}+\cdots+a_{n} x_{n}+b=0\right):=\left\{x_{i} \mid a_{i} \neq 0\right\}$, and $m\left(a_{1} x_{1}=-a_{2} x_{2}-\cdots-a_{n} x_{n}-b\right):=\left\{x_{1}\right\}$

Order facts by $\succ^{m}$ on their measures
Measure of a proof := measure of all facts used in it
Deduce $\frac{C:=\{\ldots, a x=Y, b x=Z, \ldots\}}{C \cup\{b Y-a Z=0\}}$
Now, we only need to overlap on largest $x$

Procedure for solving equations (triangular form)

## Example: Solving Linear Equations

Example: Ordering $x \succ y$

$$
\begin{gathered}
x+2 y=0, x-y=0 \\
\hline x \rightarrow-2 y, x \rightarrow y \\
\hline x \rightarrow-2 y,-2 y=y \\
\hline x \rightarrow-2 y,-3 y \rightarrow 0
\end{gathered}
$$

This is a solved/triangular form

## Linear Arithmetic Simplex

Consider equality and inequality facts, $x_{i}>0$
We are interested in whether the facts together are consistent
How can rewriting help?
First, note that:

$$
p_{1}=0, p_{2}=0, x_{1}>0, x_{2}>0 \text { is unsatisfiable iff } \exists p:
$$

(1) $p_{1}=0 \wedge p_{2}=0 \Rightarrow p=0$
(2) $x_{1}>0 \wedge x_{2}>0 \Rightarrow p>0$

How to determine if such a $p$ exists?
Key idea from rewriting: Make this witness smaller.

## Example: Linear Arithmetic Simplex

Example:

Ordering: $x \succ y$

$$
\begin{gathered}
x+2 y=0, x-y=0, x>0 \\
\hline x \rightarrow-2 y, x \rightarrow y, x>0 \\
\hline x \rightarrow-2 y,-2 y=y, x>0 \\
x \rightarrow-2 y,-3 y \rightarrow 0, x>0
\end{gathered}
$$

No contradiction detected.

Ordering: $y \succ x$

| $\frac{x+2 y=0, x-y=0, x>0}{2 y \rightarrow-x, y \rightarrow x, x>0}$ |
| :---: |
| $2 y \rightarrow-x,-x=2 x, x>0$ |
| $2 y \rightarrow-x, 3 x=0, x>0$ |
| $\perp$ |
| Contradiction detected. |

$3 x=2(x-y)+(x+2 y)$ is the required witness for unsatisfiability.
Simplex: Changing ordering (aka pivoting) helps us detect unsatisfiability

## Nonlinear Equations

Algorithm for computing Gröbner basis is a completion algorithm

Idea behind completion:

- Starting with a set of facts
- Add new facts (saturation)
- that do not have a smaller proof using existing facts
- Delete any fact (simplification)
- that do have a smaller proof using other facts


## Gröbner Basis: Example

Ordering: Total degree lex with precedence $x \succ y$
View as completion enables optimizations
$\frac{x y^{2}-x=0, x^{2} y-y^{2}=0}{x y^{2} \rightarrow x, x^{2} y \rightarrow y^{2}}$
$\frac{x y^{2} \rightarrow x, x^{2} y \rightarrow y^{2}[y], x^{2}=y^{3}}{x y^{2} \rightarrow x, x^{2} y \rightarrow y^{2}[y], y^{3} \rightarrow x^{2}}$
$\frac{x y^{2} \rightarrow x[y], x^{2} y \rightarrow y^{2}[y], y^{3} \rightarrow x^{2}, x y=x^{3}}{x y^{2} \rightarrow x[y], x^{2} y \rightarrow y^{2}[y], y^{3} \rightarrow x^{2}, x^{3} \rightarrow x y}$
$x y^{2} \rightarrow x\left[y, x^{2}\right], x^{2} y \rightarrow y^{2}[y, x], y^{3} \rightarrow x^{2}, x^{3} \rightarrow x y$

## Property of Gröbner Basis

If

$$
\begin{aligned}
p^{\prime} & \in \operatorname{Ideal}(P) \\
G & : \text { Gröbner basis for } P
\end{aligned}
$$

Then

$$
\begin{array}{cccc}
p^{\prime} & \leftrightarrow_{P}^{*} & 0 & \text { definition of ideal } \\
p^{\prime} & \rightarrow_{G}^{*} & 0 & \text { definition of GB }
\end{array}
$$

Claim. If there is no $p^{\prime \prime} \prec p^{\prime}$ s.t. $p^{\prime \prime} \in \operatorname{Ideal}(P)$, then $p^{\prime} \in G$. Proof. If $p^{\prime} \rightarrow_{G} p^{\prime \prime} \rightarrow_{G}^{*} 0$, then $p^{\prime} \succ p^{\prime \prime}$ and both $p^{\prime}, p^{\prime \prime} \in \operatorname{Ideal}(P)$.

## Nonlinear Simplex

We can generalize the idea of Simplex for linear constraints to nonlinear constraints

Problem: Given a set of nonlinear equations and inequalities:

$$
\begin{array}{ll}
p=0, & p \in P \\
q>0, & q \in Q \\
r \geq 0, & r \in R
\end{array}
$$

where $P, Q, R \subset \mathbb{Q}[\vec{x}]$ are sets of polynomials over $\vec{x}$

Is the above set unsatisfiable over the reals?

## Nonlinear Simplex: Examples

Examples of satisfiable constraints:

$$
\begin{aligned}
& \left\{x^{2}=2\right\} \\
& \left\{x^{2}=2, \quad x<0, y \geq x\right\}
\end{aligned}
$$

Examples of unsatisfiable constraints:

$$
\begin{aligned}
& \left\{x^{2}=-2, y \geq x\right\} \\
& \left\{x^{2}=2, \quad 2 x>3\right\}
\end{aligned}
$$

Applications in: control, robotics, solving games, static analysis, hybrid systems,

## Nonlinear Simplex: Known Results

- The full FO theory of reals is decidable [Tarski48]

Nonelementary decision procedure, impractical

- Double-exponential time decision procedure [Collins74, MonkSolovay74]
- Exponential space lower bound
- Collin's algorithm based on "cylindrical algebraic decomposition" has been improved over the years and implemented in QEPCAD. In practice, could fail on $p>0 \wedge p<0$.

Obtaining efficient, sound and complete method unlikely
SMT+/SMT-: Can we obtain efficiency by relaxing completeness?

## Nonlinear Simplex-

The approach is reminiscent of Simplex

- Introduce slack variables s.t. all inequality constraints are of the form $v>0$, or $w \geq 0$

$$
\begin{array}{llll}
P=0, & Q>0, & R \geq 0 & \mapsto \\
\underline{P=0}, & \underline{Q-\vec{v}=0}, & \underline{R-\vec{w}=0}, & \vec{v}>0, \vec{w} \geq 0
\end{array}
$$

- Search for a polynomial $p$ s.t.

$$
\begin{array}{r}
P=0 \wedge Q=\vec{v} \wedge R=\vec{w} \quad \Rightarrow \quad p=0 \\
\vec{v}>0, \vec{w} \geq 0 \quad \Rightarrow \quad p>0
\end{array}
$$

- If we find such a $p$, return "unsatisfiable" else return "maybe satisfiable"


## How to search for $p$ ?

Witness for unsatisfiability $p$ satisfies:

$$
\begin{align*}
P=0 \wedge Q=\vec{v} \wedge R=\vec{w} & \Rightarrow p=0  \tag{1}\\
\vec{v}>0, \vec{w} \geq 0 & \Rightarrow \quad p>0 \tag{2}
\end{align*}
$$

We need efficient sufficient checks

Sufficient check for Condition ??: $\quad p \in \operatorname{Ideal}(P, Q-\vec{v}, R-\vec{w})$
Sufficient check for Condition ??: $\quad p$ is a positive polynomial over $\vec{v}, \vec{w}$

To search for $p$, compute the Gröbner basis for $P$ making $\vec{v}, \vec{w}$ smaller in the ordering

## Example: Easy Instance

Consider $E=\left\{x^{3}=x, x>2\right\}$.

$$
\begin{array}{ll}
x^{3}-x=0, & x-v-2=0 \\
\hline(v+2)^{3}-(v+2)=0, & x-v-2=0 \\
\hline v^{3}+6 v^{2}+11 v+6=0, & x-v-2=0 \\
\hline & \perp
\end{array}
$$

Computing GB and projecting it onto the slack variables discovers the witness $p$ for unsatisfiability

May not work always ...

## Example: Harder Instance

Let $I=\left\{v_{1}>0, v_{2}>0, v_{3}>0\right\}$.

| $v_{1}+v_{2}-1=0$, | $v_{1} v_{3}+v_{2}-v_{3}-2=0$ |
| :--- | :--- |
| $v_{1}+v_{2}-1=0$, | $\left(1-v_{2}\right) v_{3}+v_{2}-v_{3}-2=0$ |
| $v_{1}+v_{2}-1=0$, | $v_{2} v_{3}-v_{2}+2=0$ |

This is a Gröbner basis.

There is an unsatisfiability witness $p$ for this example, but we failed to find it. Define $v_{2} v_{3}=v_{4}$ and make $v_{2} \succ v_{4}$ :

$$
\begin{array}{ll}
v_{1}+v_{2}-1=0, & -v_{2}+v_{4}+2=0 \\
\hline \underline{v_{1}+\left(v_{4}+2\right)-1=0,} & -v_{2}+v_{4}+2=0
\end{array}
$$

## Nonlinear Simplex: Summary

- Turn all inequalities into equations by introducing slack variables
- Compute Gröbner basis of the equations
- If a positive polynomial is ever generated, return unsatisfiable
- If not, introduce new definitions to try different orderings and repeat


## Invariant Generation for Dynamical Systems

Problem: Given a continuous dynamical system, find its invariants.
Instance: Given $\operatorname{CDS} \frac{d x}{d t}=y, \frac{d y}{d t}=-x$, find $p$ s.t. $\frac{d p}{d t}=0$
Solution: Make $d(p)$ terms smaller than others.

$$
\begin{gathered}
d(x)=y, d(y)=-x, d\left(x^{2}\right)=x * d(x), d\left(y^{2}\right)=y * d(y) \\
\hline y \rightarrow d(x), x \rightarrow-d(y), x * d(x) \rightarrow d\left(x^{2}\right), y * d(y) \rightarrow d\left(y^{2}\right) \\
\hline \ldots \text { completion... } \\
d\left(x^{2}\right)+d\left(y^{2}\right)=0
\end{gathered}
$$

The invariant $x^{2}+y^{2}=c$ is discovered

## Other Applications

There are plenty of other applications of rewriting

- Within SMT solvers: Due to incrementality and backtracking requirements, completion-based decision procedures are preferred
- Program analysis/Logical interpretation: Uninterpreted functions is a common abstraction

$$
\begin{aligned}
x:=x * y & \mapsto \quad x:=f(x, y) \\
x:=x \rightarrow \operatorname{next} & \mapsto \quad x:=\operatorname{next}(x)
\end{aligned}
$$

Equality assertion checking: equational reasoning/unification (STGs)
Interprocedural analysis: context unification

- Theorem proving: ordered resolution
- Rewriting


## Conclusion

From numeric-centric to symbolic-centric:
Rewriting an important symbolic approach

Future directions:

- Stochastic rewrite systems, SSA, Bayesian networks
- Approximate reachability using constraint solving/ abstractions
- Playing with orderings- more algorithms to be discovered?

Other topics:

- Confluence: Basic concepts?
- Learning: personalized therapeutics
- Dynamical systems

