Rewriting in Practice

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Enormous amounts of data being generated

- DNA sequencing: Fully sequencing genomes is rapid and easy
- DNA microarray: Which genes are being transcribed
- Proteomics: Which proteins are present
- Flow cytometry: Concentration in individual cells

And how to use it to predict clinical observations and phenotypes?



Model-based development

Also, a common feature in embedded system design

Goal: Models can help

- perform *in-silico* experiments
- guide wet lab experiments
- suggest novel drug targets

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Nutrient Sets

Goal: Starting from the genome, find nutrient sets on which that organism will grow

- Sequence genome of the organism
- Extract genes
- Predict metabolic network
- Predict growth on nutrient sets

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Metabolic Network: Rewriting-based Modeling

Rewriting is used as a language for writing Petrinets

Petrinets: Ground AC rewrite systems with 1 AC symbol

Example:

 $a_1: A+B \rightarrow C+D$ $a_2: C+A \rightarrow E$

The numeric parameters a_1, a_2 capture relative affinity/preference/likelihood Typical metabolic networks have 1000's of reactions and metabolites

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Rewrite Rules as Models

Rewrite rules used to model

- metabolic networks
- cell signaling
- gene regulatory networks

Terms can have complex structure: compartments, binding sites

Three different semantics of these rules

- stochastic
- deterministic
- nondeterministic

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Stochastic Firing: Chemical Master Equation

Strategy for firing rewrite rules: stochastic

Physics-based models of biochemical reaction networks: stochastic Petrinets

Semantics is given using the CME

- X: set of metabolites, |X| = n; e.g. $X = \{A, B, C, D, E\}$
- R: set of reactions
- r: a reaction, element of \mathbb{N}^n ; e.g. $A + C \to E \mapsto [-1, 0, -1, 0, 1]$
- $P: \quad \text{map from } N^{+n} \times \mathbb{R}^+ \mapsto [0, 1]$

$$\frac{dP(X,t)}{dt} = \sum_{r \in R} a(P(X-r,t),r)$$

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Stochastic Firing: Example

$$a_1: A+B \rightarrow C+D \qquad a_2: C+A \rightarrow E$$

Evolving probability distribution:

	A=2,B=1,C=D=E=0	A=1,B=0,C=1,D=1,E=0	A=0,B=0,C=0,D=1,E=1
1	1	0	0
2	1/2	1/2	0
3	1/4	1/2	1/4
4	1/8	3/8	1/2
5	•••	•••	••••
6	0	0	1

Difficulty: Not enough data to know how to compute *a*

High-dimensional Markov Chain: Does not scale

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Deterministic Firing: Mass Action Dynamics

Approximation of CME using ordinary differential equations

$$a_1: A+B \rightarrow C+D \qquad a_2: C+A \rightarrow E$$

ODE model using mass action dynamics:

$$\frac{dA(t)}{dt} = -a_1 * A(t) * B(t) - a_2 * A(t) * C(t)$$

$$\frac{dB(t)}{dt} = -a_1 * A(t) * B(t)$$

$$\frac{dC(t)}{dt} = -a_2 * A(t) * C(t) + a_1 * A(t) * B(t)$$

$$\frac{dD(t)}{dt} = a_1 * A(t) * B(t)$$

$$\frac{dE(t)}{dt} = a_2 * A(t) * C(t)$$

Issue: (i) approximate (ii) Still need a_1, a_2

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Nondeterministic Firing: Rewriting

Preferable because we do not need extra parameters

Organism grows if it can produce biomass compounds starting from nutrients

This is a reachability question

Petrinet reachability is decidable, but inefficient

Example: If A, B are nutrients, and E is a biomass compound, then:

$$2A+B \ \rightarrow \ A+C+D \ \rightarrow \ E+D$$

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Reachability: Via Constraint Solving

We can perform approximate reachability via constraint solving Example:

$$A + B \rightarrow C + D \qquad \qquad C + A \rightarrow E$$

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Constraints: Suppose initial state is 2A + B, we want to reach D + E

$$A: -r_1 - r_2 + 2 = B: -r_1 + 1 = 0$$
$$C: r_1 - r_2 = 0$$
$$D: r_1 - 1 = 0$$
$$E: r_2 - 1 = 0$$

If D + E is reachable from 2A + B, then above constraints are satisfiable

This is called Flux Balance Analysis

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Nutrient Sets for E.Coli

We have used constraint solving for finding (minimal) nutrient sets for E.Coli

Flux Balance Analysis: an overapproximation of the reachability relation

We developed a constraint-based approach that captures reachability more accurately than FBA

Results:

(1) About 75% accuracy with experimental results
(2) Predicted growth of E.Coli on cynate as both Carbon and Nitrogen source, which was experimentally verified

(3) Can compute all minimal nutrient sets for E.Coli

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Rewriting in Biology

Apart from metabolic networks, rewrite rules are also commonly used for modeling signalling pathways

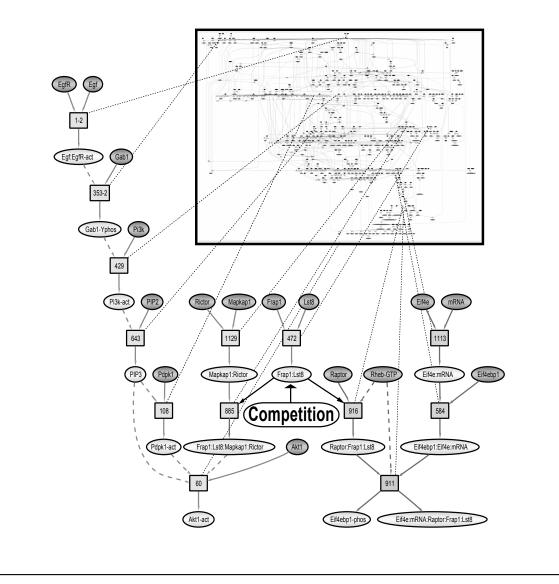
Signaling pathway: Biochemical reactions that show how signals are transmitted from the cell surface to the cell cytoplasm to nucleus

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Questions of interest to biologists vary
visualization
reachability pathways
conflicts: A \rightarrow^* C and B \rightarrow^* D, but A + B - (A \cap B) \not\rightarrow^* C + D
knockouts: Is it possible A \rightarrow^* C, but without using B
```

All analysis techniques should scale

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Competing Rules in EGF Stimulation Pathway



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Rewriting in

- Systems Biology
- Algorithm Description and Design
- Theorem Proving

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Algorithms

Rewriting is useful in two different ways in the study of algorithms:

- Rewriting-based descriptions for algorithms
- Rewriting as a paradigm for algorithm design

Rewriting-based Descriptions

- Express the algorithmic problem by identifying the term structure of initial and final configuration
- Define an ordering on the space of configurations such that the final configuration is minimal
- Find local transition rules that decrease configuration measure

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Rewriting-based Descriptions

Such descriptions are obtained when writing algorithms in rewriting logic (such as, in Maude)

Example: Sorting can be described by

$$X, a, Y, b, Z \rightarrow X, b, Y, a, Z \text{ if } a > b$$

Benefit:

- Separates implementation from the algorithm
- Correctness argument simpler
- Algorithms are nondeterministic

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Algorithmic Design Paradigms

Some paradigms taught in a course on algorithms:

- greedy
- divide and conquer
- dynamic programming
- branch and bound

One important paradigm often not taught:

• completion

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Completion as Paradigm

for Algorithm Design

- Express the algorithmic problem by identifying configurations as sets of facts
- Define an ordering on the facts and proofs
- Find local transition rules that add or delete facts such that
 - \circ proofs of (provable) facts do not get any bigger
 - some proof gets smaller

In the final configuration, all facts have minimal proofs

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$$\begin{array}{l} \hline \textbf{Completion-based Procedures: Examples} \\ \hline \textbf{Shortest-path in a graph:} \\ \hline \textbf{Deduce} & \frac{C := \{\dots, \texttt{path}(u, v, d_{uv}), \texttt{path}(v, w, d_{vw}), \dots\}}{C \cup \{\texttt{path}(u, w, d_{uv} + d_{vw})\}} \\ \hline \textbf{Delete} & \frac{C := \{\dots, \texttt{path}(u, v, d), \texttt{path}(u, v, d'), \dots\}}{C - \{\texttt{path}(u, v, d')\}} \texttt{if } d < d' \end{array}$$

Orderings determine what deduction and deletion steps are acceptable

Deleted facts should have smaller proof using remaining facts

Deduced facts should make some proof smaller

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Benefits

- Uniform understanding of several algorithms
- Different orderings will yield different algorithms
- Strategy for applying the inference steps can be determined by other factors

Can optimize an algorithm by

- choosing an appropriate ordering
- choosing an appropriate strategy
- choosing an appropriate data structure

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Completion-based Algorithms

- Union-find
- Congruence closure
- Rational linear arithmetic (Simplex)
- Fourier-Motzkin
- Gröbner basis
- Ordered resolution

In this talk,

- Linear equalities
- Linear equalities + inequalities
- Nonlinear equalities
- Nonlinear equalities + inequalities

Solving Linear Equations

Facts: $a_1x_1 + \dots + a_nx_n + b = 0$

Pick an ordering $x_1 \succ x_2 \succ \cdots \succ x_n$

Define measure $m(a_1x_1 + \dots + a_nx_n + b = 0) := \{x_i \mid a_i \neq 0\}$, and $m(x_i > 0) := \{x_i\}$

Order facts by \succ^m on their measures

Measure of a proof := measure of all facts used in it

Deduce
$$\frac{C := \{\dots, ax + Y = 0, bx + Z = 0, \dots\}}{C \cup \{bY - aZ = 0\}}$$

But, here, we need to do this even when x is not maximal

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Solving Linear Arithmetic Equations

Get more flexibility in ordering facts

Distinguish: $a_1x_1 + \cdots + a_nx_n + b = 0$ and $a_1x_1 = -a_2x_2 - \cdots - a_nx_n - b$

Pick an ordering $x_1 \succ x_2 \succ \cdots \succ x_n$

Define measure $m(a_1x_1 + \dots + a_nx_n + b = 0) := \{x_i \mid a_i \neq 0\}$, and $m(a_1x_1 = -a_2x_2 - \dots - a_nx_n - b) := \{x_1\}$

Order facts by \succ^m on their measures

Measure of a proof := measure of all facts used in it

Deduce
$$\frac{C := \{\dots, ax = Y, bx = Z, \dots\}}{C \cup \{bY - aZ = 0\}}$$

Now, we only need to overlap on largest x

Procedure for solving equations (triangular form)

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Example: Solving Linear Equations

Example: Ordering $x \succ y$

$$\frac{x + 2y = 0, \ x - y = 0}{x \to -2y, \ x \to y}$$
$$\frac{x \to -2y, \ -2y = y}{x \to -2y, \ -3y \to 0}$$

This is a solved/triangular form

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Linear Arithmetic Simplex

Consider equality and inequality facts, $x_i > 0$

We are interested in whether the facts together are consistent How can rewriting help?

First, note that:

$$p_1 = 0, \ p_2 = 0, \ x_1 > 0, \ x_2 > 0$$
 is unsatisfiable iff $\exists p :$
(1) $p_1 = 0 \land p_2 = 0 \Rightarrow p = 0$
(2) $x_1 > 0 \land x_2 > 0 \Rightarrow p > 0$

How to determine if such a *p* exists?

Key idea from rewriting: Make this witness smaller.

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Example: Linear Arithmetic Simplex

Example:

Ordering: $x \succ y$	Ordering: $y \succ x$
$\frac{x + 2y = 0, \ x - y = 0, \ x > 0}{x \to -2y, \ x \to y, \ x > 0}$ $\frac{x \to -2y, \ -2y = y, \ x > 0}{x \to -2y, \ -3y \to 0, \ x > 0}$	$x + 2y = 0, \ x - y = 0, \ x > 0$ $2y \rightarrow -x, \ y \rightarrow x, \ x > 0$ $2y \rightarrow -x, \ -x = 2x, \ x > 0$ $2y \rightarrow -x, \ 3x = 0, \ x > 0$ \bot

No contradiction detected.

Contradiction detected.

3x = 2(x - y) + (x + 2y) is the required witness for unsatisfiability.

Simplex: Changing ordering (aka pivoting) helps us detect unsatisfiability

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Nonlinear Equations

Algorithm for computing Gröbner basis is a completion algorithm

Idea behind completion:

- Starting with a set of facts
- Add new facts (saturation)
 - that do not have a smaller proof using existing facts
- Delete any fact (simplification)
 - that do have a smaller proof using other facts

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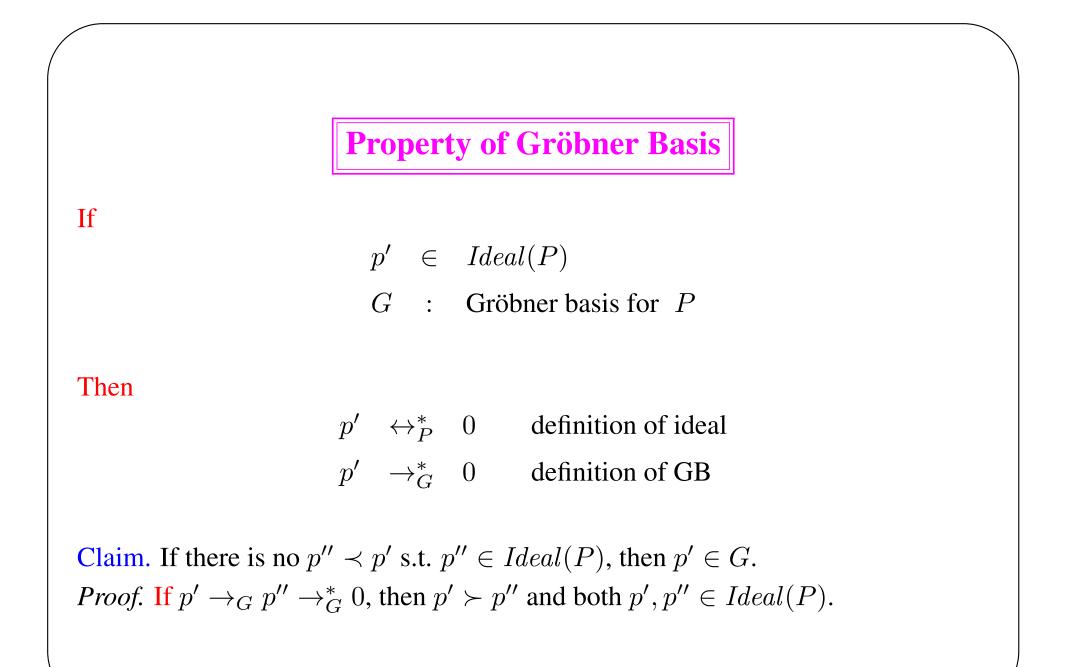
Gröbner Basis: Example

Ordering: Total degree lex with precedence $x \succ y$

View as completion enables optimizations

$xy^2 - x = 0, \ x^2y - y^2 = 0$
$xy^2 \to x, \ x^2y \to y^2$
$xy^2 \rightarrow x, \ x^2y \rightarrow y^2[y], \ x^2 = y^3$
$xy^2 \to x, \ x^2y \to y^2[y], \ y^3 \to x^2$
$xy^2 \rightarrow x[y], \ x^2y \rightarrow y^2[y], \ y^3 \rightarrow x^2, \ xy = x^3$
$xy^2 \rightarrow x[y], \ x^2y \rightarrow y^2[y], \ y^3 \rightarrow x^2, \ x^3 \rightarrow xy$
$xy^2 \rightarrow x[y, x^2], \ x^2y \rightarrow y^2[y, x], \ y^3 \rightarrow x^2, \ x^3 \rightarrow xy$

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Nonlinear Simplex

We can generalize the idea of Simplex for linear constraints to nonlinear constraints

Problem: Given a set of nonlinear equations and inequalities:

$$p = 0, \qquad p \in P$$
$$q > 0, \qquad q \in Q$$
$$r \ge 0, \qquad r \in R$$

where $P, Q, R \subset \mathbb{Q}[\vec{x}]$ are sets of polynomials over \vec{x}

Is the above set unsatisfiable over the reals?

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Nonlinear Simplex: Examples

Examples of satisfiable constraints:

$$\{x^2 = 2\}$$

$$\{x^2 = 2, x < 0, y \ge x\}$$

Examples of unsatisfiable constraints:

$$\{x^2 = -2, \ y \ge x\}$$
$$\{x^2 = 2, \ 2x > 3\}$$

Applications in: control, robotics, solving games, static analysis, hybrid systems,

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Nonlinear Simplex: Known Results

- The full FO theory of reals is decidable [Tarski48] Nonelementary decision procedure, impractical
- Double-exponential time decision procedure [Collins74, MonkSolovay74]
- Exponential space lower bound
- Collin's algorithm based on "cylindrical algebraic decomposition" has been improved over the years and implemented in QEPCAD.
 In practice, could fail on p > 0 ∧ p < 0.

Obtaining efficient, sound and complete method unlikely

SMT+/SMT-: Can we obtain efficiency by relaxing completeness?

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Nonlinear Simplex-

The approach is reminiscent of Simplex

• Introduce slack variables s.t. all inequality constraints are of the form v > 0, or $w \ge 0$

$$P = 0, \quad Q > 0, \qquad R \ge 0 \qquad \mapsto$$
$$\underline{P = 0}, \quad \underline{Q - \vec{v} = 0}, \quad \underline{R - \vec{w} = 0}, \quad \vec{v} > 0, \quad \vec{w} \ge 0$$

• Search for a polynomial *p* s.t.

$$P = 0 \land Q = \vec{v} \land R = \vec{w} \quad \Rightarrow \quad p = 0$$
$$\vec{v} > 0, \ \vec{w} \ge 0 \quad \Rightarrow \quad p > 0$$

• If we find such a *p*, return "unsatisfiable" else return "maybe satisfiable"

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How to search for *p***?**

Witness for unsatisfiability *p* satisfies:

$$P = 0 \land Q = \vec{v} \land R = \vec{w} \quad \Rightarrow \quad p = 0 \tag{1}$$

$$\vec{v} > 0, \ \vec{w} \ge 0 \quad \Rightarrow \quad p > 0$$
 (2)

We need efficient sufficient checks

Sufficient check for Condition ??: $p \in Ideal(P, Q - \vec{v}, R - \vec{w})$ Sufficient check for Condition ??:p is a positive polynomial over \vec{v}, \vec{w}

To search for p, compute the Gröbner basis for P making \vec{v}, \vec{w} smaller in the ordering

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Example: Easy Instance

Consider $E = \{x^3 = x, x > 2\}.$

$$x^{3} - x = 0, \qquad x - v - 2 = 0$$

$$(v + 2)^{3} - (v + 2) = 0, \qquad x - v - 2 = 0$$

$$v^{3} + 6v^{2} + 11v + 6 = 0, \qquad x - v - 2 = 0$$

$$\bot$$

Computing GB and projecting it onto the slack variables discovers the witness p for unsatisfiability

May not work always ...

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Example: Harder Instance

Let $I = \{v_1 > 0, v_2 > 0, v_3 > 0\}.$

 $\begin{array}{cc} v_1 + v_2 - 1 = 0, & v_1 v_3 + v_2 - v_3 - 2 = 0 \\ \hline v_1 + v_2 - 1 = 0, & (1 - v_2)v_3 + v_2 - v_3 - 2 = 0 \\ \hline v_1 + v_2 - 1 = 0, & v_2 v_3 - v_2 + 2 = 0 \end{array}$

This is a Gröbner basis.

There is an unsatisfiability witness p for this example, but we failed to find it. Define $v_2v_3 = v_4$ and make $v_2 \succ v_4$:

$$v_1 + v_2 - 1 = 0,$$
 $-v_2 + v_4 + 2 = 0$
 $\underline{v_1 + (v_4 + 2) - 1 = 0},$ $-v_2 + v_4 + 2 = 0$

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Nonlinear Simplex: Summary

- Turn all inequalities into equations by introducing slack variables
- Compute Gröbner basis of the equations
- If a positive polynomial is ever generated, return unsatisfiable
- If not, introduce new definitions to try different orderings and repeat

Invariant Generation for Dynamical Systems

Problem: Given a continuous dynamical system, find its invariants. Instance: Given CDS $\frac{dx}{dt} = y$, $\frac{dy}{dt} = -x$, find p s.t. $\frac{dp}{dt} = 0$

Solution: Make d(p) terms smaller than others.

$$\begin{aligned} d(x) &= y, \ d(y) = -x, \ d(x^2) = x * d(x), \ d(y^2) = y * d(y) \\ y &\to d(x), \ x \to -d(y), \ x * d(x) \to d(x^2), \ y * d(y) \to d(y^2) \\ & \text{...completion...} \end{aligned}$$

$$d(x^2) + d(y^2) = 0$$

The invariant $x^2 + y^2 = c$ is discovered

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Other Applications

There are plenty of other applications of rewriting

- Within SMT solvers: Due to incrementality and backtracking requirements, completion-based decision procedures are preferred
- Program analysis/Logical interpretation: Uninterpreted functions is a common abstraction

 $\begin{aligned} x &:= x * y &\mapsto \quad x := f(x, y) \\ x &:= x \to \texttt{next} &\mapsto \quad x := \texttt{next}(x) \end{aligned}$

Equality assertion checking: equational reasoning/unification (STGs) Interprocedural analysis: context unification

- Theorem proving: ordered resolution
- Rewriting

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Conclusion

From numeric-centric to symbolic-centric: Rewriting an important symbolic approach

Future directions:

- Stochastic rewrite systems, SSA, Bayesian networks
- Approximate reachability using constraint solving/ abstractions
- Playing with orderings– more algorithms to be discovered?

Other topics:

- Confluence: Basic concepts?
- Learning: personalized therapeutics
- Dynamical systems

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