

Automating Compositional Verification

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collaborators

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state-explosion problem



compositional verification

does system made up of M_1 and M_2 satisfy property P?



- check P on entire system: too many states!
 use system's natural decomposition into components to break-up the verification task
- check components in isolation:

does M₁ satisfy P?

"when we try to pick out anything by itself, we find it hitched to everything else in the universe" John Muir introduces assumptions / reasons about triples:



how do we come up with the assumption?

the weakest assumption [ASE 2002]



- given component M, property P, and the interface \sum of M with its environment, generate the weakest environment assumption WA such that: $\langle WA \rangle M \langle P \rangle$ holds
- weakest means that for all environments E:

 $\langle true \rangle M \parallel E \langle P \rangle \parallel FF \langle true \rangle E \langle WA \rangle$

weakest assumption in AG reasoning

$$\begin{array}{c|c} I. & \langle A \rangle & M_1 & \langle P \rangle \\ \hline 2. & \langle true \rangle & M_2 & \langle A \rangle \\ \hline & \langle true \rangle & M_1 & || & M_2 & \langle P \rangle \end{array}$$

weakest assumption makes rule complete

for all E,
$$\langle true \rangle$$
 M || E $\langle P \rangle$ IFF $\langle true \rangle$ E $\langle WA \rangle$

$$\langle true \rangle M_1 \parallel M_2 \langle P \rangle IFF \langle true \rangle M_2 \langle WA \rangle$$

in other words:

 $\langle true \rangle M_2 \langle WA \rangle$ holds implies $\langle true \rangle M_1 \parallel M_2 \langle P \rangle$ holds $\langle true \rangle M_2 \langle WA \rangle$ not holds implies $\langle true \rangle M_1 \parallel M_2 \langle P \rangle$ not holds

formalisms

- components modeled as finite state machines (FSM)
 - FSMs assembled with parallel composition operator "||"
 - synchronizes shared actions, interleaves remaining actions
- a safety property P is a FSM
 - P describes all legal behaviors in terms of its alphabet
 - $P_{err} complement of P$
 - determinize & complete P with an "error" state;
 - bad behaviors lead to error
 - component M satisfies P iff error state unreachable in (M || P_{err})
- assume-guarantee reasoning
 - assumptions and guarantees are FSMs
 - $\langle A \rangle M \langle P \rangle$ holds iff error state unreachable in (A || M || P_{err})

example







parallel composition





property satisfaction



crex. I: (I_0 , O_0) out (I_0 , O_{error}) *crex. 2*: (I_0 , O_0) in (I_1 , O_1) send (I_2 , O_1) out (I_2 , O_0) out (I_2 , O_{error})

assume-guarantee reasoning



crex I: (I_0 , A_0 , O_0) out **X** *crex 2*: (I_0 , A_0 , O_0) in (I_1 , A_0 , O_1) send (I_2 , A_1 , O_1) out (I_2 , A_0 , O_0) out **X**

learning assumptions [TACAS 2003]

iterative solution + intermediate results

L* learns unknown regular language U (over alphabet Σ) and produces minimal DFA A such that L(A) = U (L* originally proposed by Angluin)



the oracle

queries: should word w be included in L(A)?

yes / no

yes!

conjectures: here is an A – is L(A) = U?

no: word w should (not) be in L(A)

oracle for WA in assume-guarantee reasoning



 $\begin{array}{l} \left< WA \right> M_1 \left< P \right> \text{ holds} \\ \left< true \right> M_2 \left< WA \right> \text{ holds implies } \left< true \right> M_1 \mid\mid M_2 \left< P \right> \text{ holds} \\ \left< true \right> M_2 \left< WA \right> \text{ does not hold implies } \left< true \right> M_1 \mid\mid M_2 \left< P \right> \text{ does not hold} \end{array}$

assumptions conjectured by L* are not comparable semantically

- ► terminates with *minimal* automaton A for U
- ▶ generates DFA candidates $A_i: |A_1| < |A_2| < ... < |A|$
- produces at most n candidates, where n = |A|
- # queries: O(kn² + n logm),
 - m is size of largest counterexample, k is size of alphabet
- for assume-guarantee reasoning, may terminate early with a smaller assumption than the weakest

example



we check: $\langle true \rangle$ Input || Output $\langle Order \rangle$ M₁ = Input, M₂ = Output, P = Order

assumption alphabet: {send, out, ack}

queries







		Ε
	Table T	λ
S	λ	true
	out	false
S·Σ	ack	true
	out	false
	send	true
	out, ack	false
	out, out	false
	out, send	false

S = set of prefixes E = set of suffixes

candidate construction









counterexamples add to S

S = set of prefixes E = set of suffixes

conjectures



more than 2 components [TACAS03, FMSD09]



symmetric rules: motivation







 M_1 = Input, M_2 = Output, P = Order





 M_1 = Output, M_2 = Input, P = Order



symmetric learning framework [SAVCBS05]



interfaces



- beyond syntactic interfaces (open file before close)
- document implicit assumptions
- safe: accept NO illegal sequence of calls
- permissive: accept ALL legal sequences of calls
- safe & permissive interface = weakest assumption



the oracle

yes /

es.

(queries)

should word w be included in L(A)?

(conjectures)

here is an A - is L(A) = U?

(is A safe and permissive?)

no: word w should (not) be in L(A)

checkSafe(interface A, FSM M)



checkPermissive(interface A, FSM M)



permissiveness heuristics [FASE 2009]



remember, it's a heuristic



JavaPathfinder UML statecharts

assume-guarantee reasoning

interface generation / discharge

jpf-cv http://babelfish.arc.nasa.gov/trac/jpf

infinite components [CAV 2010]

• use predicate abstraction (e.g., $x \ge 0$, x < 0)



an interface safe w.r.t. C^{may} and permissive w.r.t. C^{must} is safe and permissive w.r.t. concrete component C

$Query(\sigma, C)$

- I. if checkSafe(σ ,C^{must}) != null
- 2. return "no"
- 3. cex = checkSafe(σ ,C^{may})
- 4. if cex == null
- 5. return "yes"
- 6. Preds = Preds U Refine(cex)
- 7. Query(σ , C)



If concrete component is deterministic, so is the must abstraction... ARMC model checker: Java2SDK library classes, OpenSSL, NASA CEV model

related work

- assume-guarantee reasoning for code (ICSE 2004, SAVCBS 2005, IET Software 2009)
- learning with alphabet refinement (TACAS 2007; also Chaki et al.)
- learning assumptions for interface automata (FM 2008)
- assume-guarantee abstraction refinement (CAV 2008)
- compositional verification in symbolic setting (Alur et al. 05)
- ▶ minimal assumptions as separating automata for languages $L(M_2)$ and $L(M_1) \cap L(coP)$ (Gupta et al. 07, Chen et al. 09)
- learning omega-regular languages for liveness (Farzan et al. 08)
- learning non-deterministic automata (Bollig et al. 09)
- Iearning Boolean functions (Chen et al. 10)
- assumption generation in probabilistic setting (Feng et al. 10)

summary and food for thought...

- techniques are generic
- better applied at design level
- not a panacea...
 - perform well when alphabets & assumptions are small
- what makes a system amenable to compositional techniques?
- design for compositional verification; combine with other design approaches
- how can we make it practical for real systems? what types of interfaces are useful in practice?
- discovering good system decompositions
- Iiveness, timed & probabilistic systems, non functional properties
- multi core / parallelization?

thank you!

invoke a model checker within a model checker?

→ MC: model check for (M_i, A_{error}) reached (err, ok) by trace t if (memoized(t) == no) // t is spurious backtrack and continue search else // memoized(t) == yes or t not in memoized model checker produces t if (query(t) == yes)return t to L* // not permissive else restart at MC

conjecture : Oracle I

- I. cex = checkSafe(A, C^{may})
- 2. if cex == null
- 3. invoke Oracle2
- 4. If Query(cex, C) == "false"
- 5. return cex to L^*
- 6. else
- 7. goto I

conjecture : Oracle 2

- I. cex = checkPermissive(A, C^{must})
- 2. if cex == null
- 3. return A
- 4. If Query(cex, C) == "true"
- 5. return cex to L^*
- 6. else
- 7. goto I

example I: Mars Exploration Rover

- tools: LTSA, SPIN
- model derived from JPL's Mars Exploration Rover (MER) Resource Arbiter
 - local management of resource contention between resource consumers (e.g. science instruments, communication systems)
 - consists of k user threads and one server thread (arbiter)
- checked mutual exclusion between resources (e.g. driving while capturing a camera image are incompatible)
- compositional verification scaled to >5 users vs. monolithic verification ran out of memory [SPIN' 06]

Resource Arbiter





example 2: autonomous rendezvous & docking

- tool: LTSA
- consists of control software, state estimator, and 4 types of sensors
- input provided as UML state-charts, properties of type:
 - "you need at least two operational sensors to proceed to next mode"
- 3 bugs detected
- scaling achieved with compositional verification:
 - monolithic verification runs out of memory after > I3M states
 - compositional verification terminates successfully in secs. Largest state-space explored is less than 60K states, as opposed to > 13M.



example 3: K9 Rover Executive

- tools: LTSA, JavaPathfinder
- model of NASA Ames K9 Rover Executive
 - executes flexible plans for autonomy
 - consists of Executive thread and ExecCondChecker thread for monitoring state conditions
 - checked for specific shared variable: if Executive reads its value, ExecCondChecker should not read the variable before the Executive clears it



- generated assumption of 6 states for model in LTSA [TACAS 2003]
- used generated assumption to check 8K lines of JAVA code translated from 10K lines of C++ code using the JavaPathfinder model checker [ICSE 2004]
- reduced memory used by JavaPathfinder > 3 times
- used generated assumption to perform assume-guarantee testing of C++ code using Eagle runtime monitoring framework [SAVCBS 2005, IET Software 2009]