

New Directions in V&V

Evidence, Arguments, and Automation

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V&V for Fault Management

Ideally, we'd like to understand, consider, examine, test

- all possible behaviors

Which raises some interesting issues

- Define all possible
- However you define it, that's a lot of behaviors
- How can we handle that many?
- Can we do it subsystem by subsystem?
- Can we start the work early?

We need a framework and some technology and a methodology

Existing Frameworks for V&V

- V&V and the larger processes of certification/approval provide assurance that deploying a given system does not pose an unacceptable risk of failure or adverse consequences
- Current methods **explicitly** depend on
 - **Standards**, regulations, process
 - Rigorous examination of the **whole, finished system**

And **implicitly** on

- **Conservative practices**
- **Safety culture**
- **All of these are changing**

The Standards-Based Approach to Software Assurance

- E.g., **airborne s/w** (DO-178B), **security** (Common Criteria)
- Developer follows a prescribed **method** (or **processes**)
 - Delivers prescribed **outputs**
 - ★ e.g., documented requirements, designs, analyses, tests and outcomes; traceability among these
- **Works well in fields that are stable or change slowly**
 - Can institutionalize lessons learned, best practice
 - ★ e.g. evolution of DO-178 from A to B to C
- **But less suitable with novel problems, solutions, methods**

A Recent Incident

- Fuel emergency on Airbus A340-642, G-VATL, on 8 February 2005 (AAIB SPECIAL Bulletin S1/2005)
- Toward the end of a flight from Hong Kong to London: two engines flamed out, crew found certain tanks were critically low on fuel, declared an emergency, landed at Amsterdam
- Two Fuel Control Monitoring Computers (FCMCs) on this type of airplane; they cross-compare and the “healthiest” one drives the outputs to the data bus
- Both FCMCs had fault indications, and one of them was unable to drive the data bus
- Unfortunately, this one was judged the healthiest and was given control of the bus even though it could not exercise it
- Further backup systems were not invoked because the FCMCs indicated they were not both failed

Implicit and Explicit Factors

- See also ATSB incident report for in-flight upset of Boeing 777, 9M-MRG (Malaysian Airlines, near Perth Australia)
- How could gross errors like these pass through rigorous assurance standards?
- Maybe effectiveness of current methods depends on implicit factors such as safety culture, conservatism
- Current business/contracting models and mission ambitions are leading to a loss of these
 - Outsourcing, COTS, complacency, innovation, complexity
- Surely, a credible certification regime should be effective on the basis of its explicit practices
- How else can we cope with the changes and challenges ahead?

Standards and Goal-Based Assurance

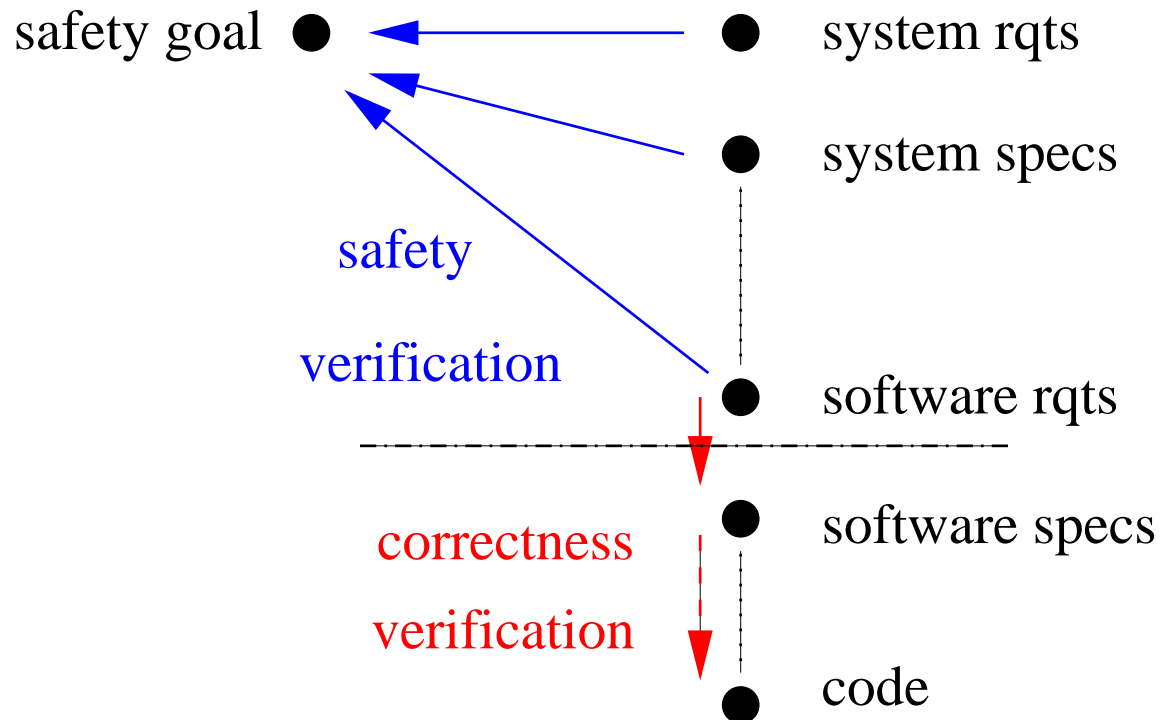
- All assurance is intellectually based on **arguments** that purport to justify certain **claims**, based on documented **evidence**
- Standards usually define only the **evidence** to be produced
- The **claims** and **arguments** are **implicit**
- Hence, hard to tell whether given **evidence meets the intent**
- E.g., is MC/DC coverage evidence for good testing or good requirements?
- Recently, **goal-based** assurance methods have been gaining favor: **these make the elements explicit**

The Goal-Based Approach to Software Assurance

- E.g., UK **air traffic management** (CAP670 SW01), UK **defence** (DefStan 00-56), growing interest elsewhere
- **Developer provides an assurance case**
 - Whose outline form may be specified by standards or regulation (e.g., 00-56)
 - Makes an **explicit** set of **goals** or **claims**
 - Provides supporting **evidence** for the claims
 - And **arguments** that **link the evidence to the claims**
 - ★ Make clear the underlying **assumptions** and **judgments**
 - ★ Should allow different viewpoints and levels of detail
- Can be specialized to safety, security, dependability cases
- The case is evaluated by **independent assessors**
- Key point: **explicit claims, evidence, argument**

Assurance Cases Allow Customization

- Standards such as DO-178B focus on **correctness**
- i.e., on **verification** more than **validation**

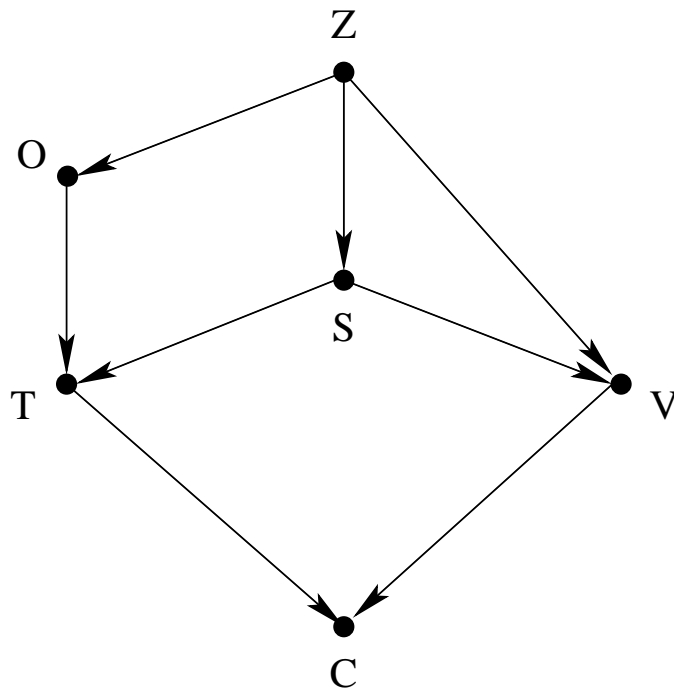


- Whereas assurance cases liberate us to **customize** our V&V

System-Focused Claims

- Goal-based assurance cases are driven by risk assessment
- Focus on hazards, risks, and their mitigations
- At the system level
- Flow down into subsystems and allow prioritization
- Multi-legged cases allow evidence for testing, say, to be combined with analysis in a rational way using Bayesian Belief Nets (BBNs)

A BBN Example



Z: System Specification

O: Test Oracle

S: System's true quality

T: Tests

V: Analysis

C: V&V decision

Example joint probability table: successful test outcome

Correct System		Incorrect System	
Correct Oracle	Bad Oracle	Correct Oracle	Bad Oracle
100%	50%	5%	30%

Technology and Automation

- Goal-based assurance cases give us a framework to approach V&V in a customized but rational way, focusing on system-level hazards
- Traditional methods for assurance at the systems level, such as hazard analysis (HA), FMEA, FTA, HAZOP
- Are really abstracted (i.e., approximate) ways to do **reachability analysis**
 - Enumeration of all the states that a system can get into through interaction with its environment
- **In other words, they are ways of exploring all possible behaviors**
- How about if we could do this for more detailed levels of design?

Informal Reachability Analysis

- Given a **system model** made up of **interacting state machines**
- i.e., the **software design**, **hardware components**
 - And the **environment**
 - Which can **inject faults** (think of it as the test harness)
- Work forward from the initial states to see if you can reach a state where something bad happens (HA)
- Or work back from the bad states to see if you can reach an initial state (FTA)
- Made feasible to do by hand by focusing on only certain transitions (FMEA)
- And by using abstracted models (HAZOP)
- But suppose we could **automate** it?

Automated Reachability Analysis

- We need “machinable” models of the system and its environment; not PowerPoint pictures, not code
- E.g., Statecharts, UML, AADL, Simulink/Stateflow
- If we “downscale” these to finite state
 - E.g., discretize continuous values
- Then we can do brute-force reachability analysis
- By running or simulating the system, backtracking to take alternate paths, and remembering where we have been
- This is what an explicit state model checker (e.g., Spin) does
- Can handle tens of millions of reachable states
- Gives counterexample when an error found
- Errors defined by observer models, or property language

Formal Reachability Analysis

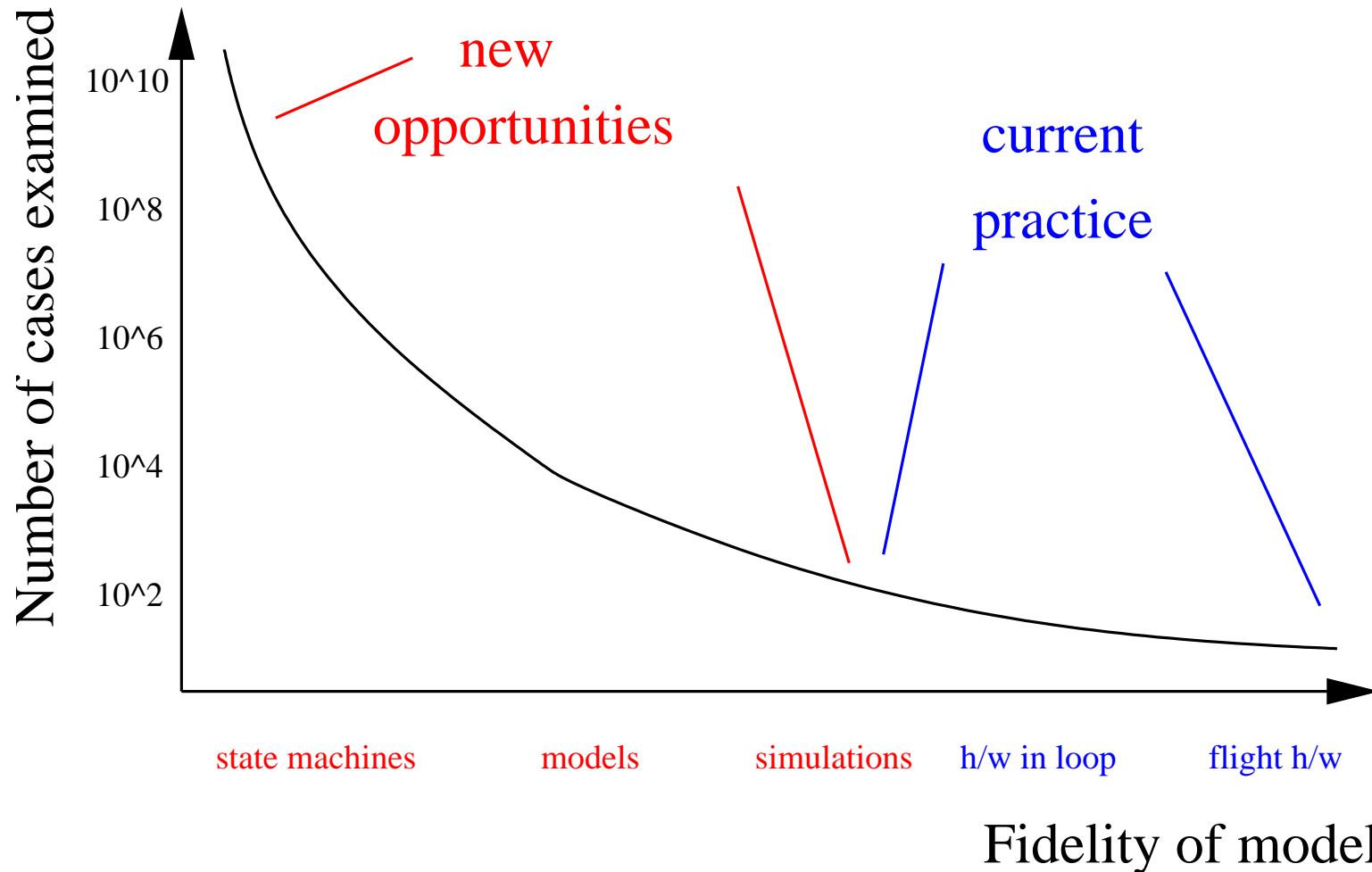
- Ten million states is only 23 or 24 state bits
- Symbolic methods of reachability analysis can often handle bigger systems. . . trillions of states, even infinite
- By representing states as **formulas** rather than explicit values
 - e.g., $x < y$ represents an infinite number of explicit states: $(0,1), (0,2), \dots (1,2), (1,3)\dots$
- **Symbolic** model checkers (e.g., nuSMV, SAL)
 - Use **Binary Decision Diagrams** (BDDs)
- **Bounded** model checkers (e.g., nuSMV, SAL)
 - Use Boolean **satisfiability** (SAT) **solvers**
- **Infinite bounded** model checkers (e.g., SAL)
 - Use solvers for **satisfiability modulo theories** (SMT)
- BDDs, SAT, SMT solvers are commodities

Reachability Analysis for Fault Management

- Construct state machine models for components, environment, the FM algorithms (e.g., monitors and responses) in some modeling notation
- Connect a model checker to the modeling tool set
 - E.g., Mathworks' own [Design Verifier](#) for Simulink/Stateflow
 - Or [build your own](#)—as Rockwell has
- And you will absolutely find large numbers of issues such as those described for New Horizons fault management, or Space Station architecture with negligible effort
- Find vastly more problems by examining [all](#) the behaviors of a simplified model than by testing [some](#) of the behaviors of the real thing

A Spectrum of V&V Activities

A **wealth of opportunities** to the left; **can apply them early**, too



Reachability Analysis for Fault Management V&V

- V&V is more than debugging
- Want to make strong inference when the model checker no longer finds bugs
- Requires judgement in modeling
 - Often less is more: constraints rather than details
- And more sophisticated automation (research topics)
 - K-induction rather than bounded model checking
 - Counterexample-guided abstraction refinement (CEGAR)
 - Hybrid systems (state machines plus differential equations)
- And we need ways to keep different models, simulations, real system in sync

Test Automation for Fault Management V&V

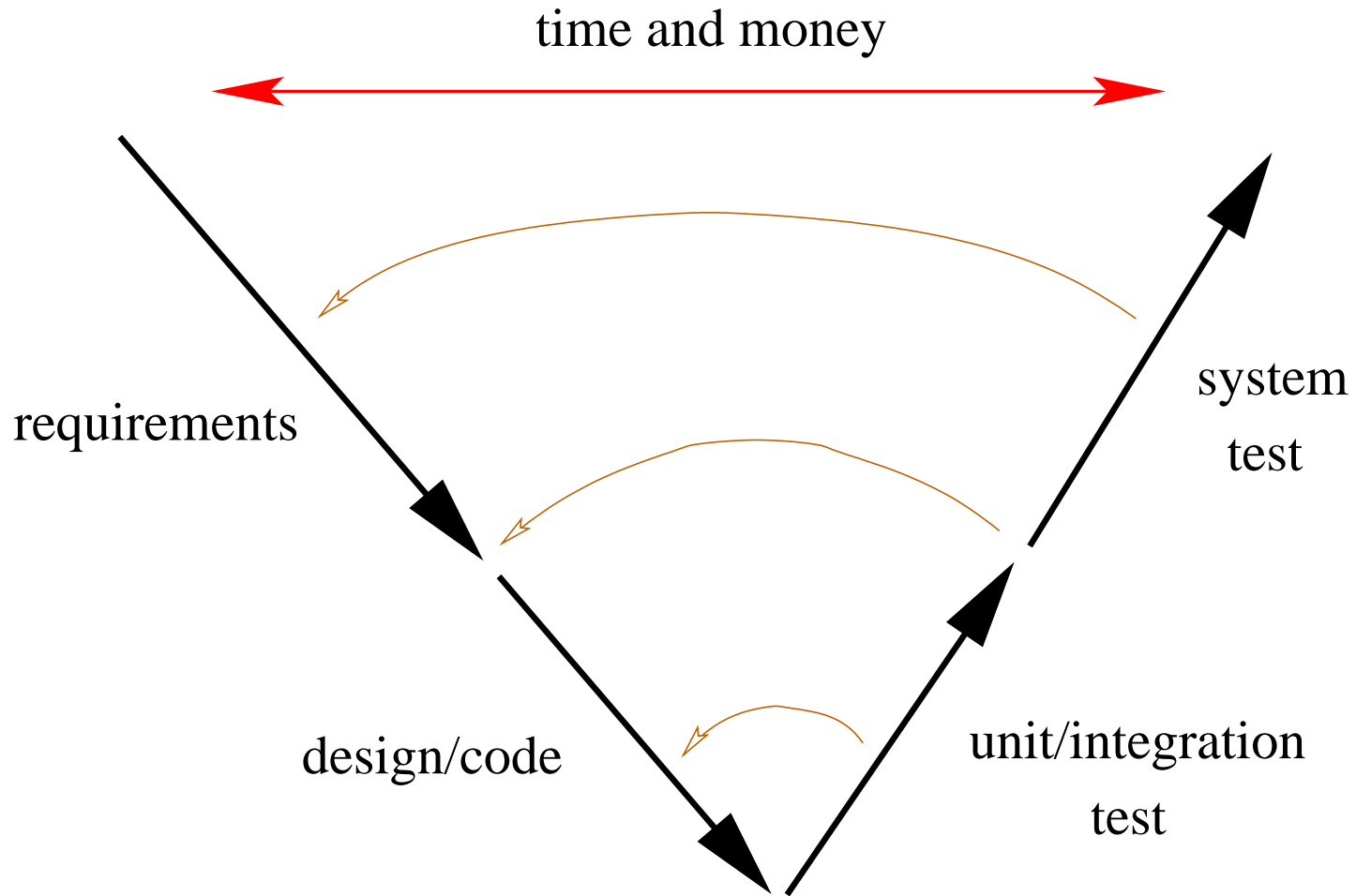
- The counterexamples from model checkers can be used to generate **test cases** to run on the **implementation**
 - Tests can target model coverage, corner cases, specific kinds of scenarios: focus shifts from constructing tests to specifying test objectives
- **Unit tests** are pretty easy to generate automatically
- **Integration tests** are more challenging
 - Depends how much control you have of other components
- **Hardware in the loop** is more difficult still (research)
 - Some of the models are hybrid systems
- **Automation can be used to extend random tests into corners**
 - There are very potent mixed **concrete symbolic** (concolic) methods

From Analysis to Synthesis

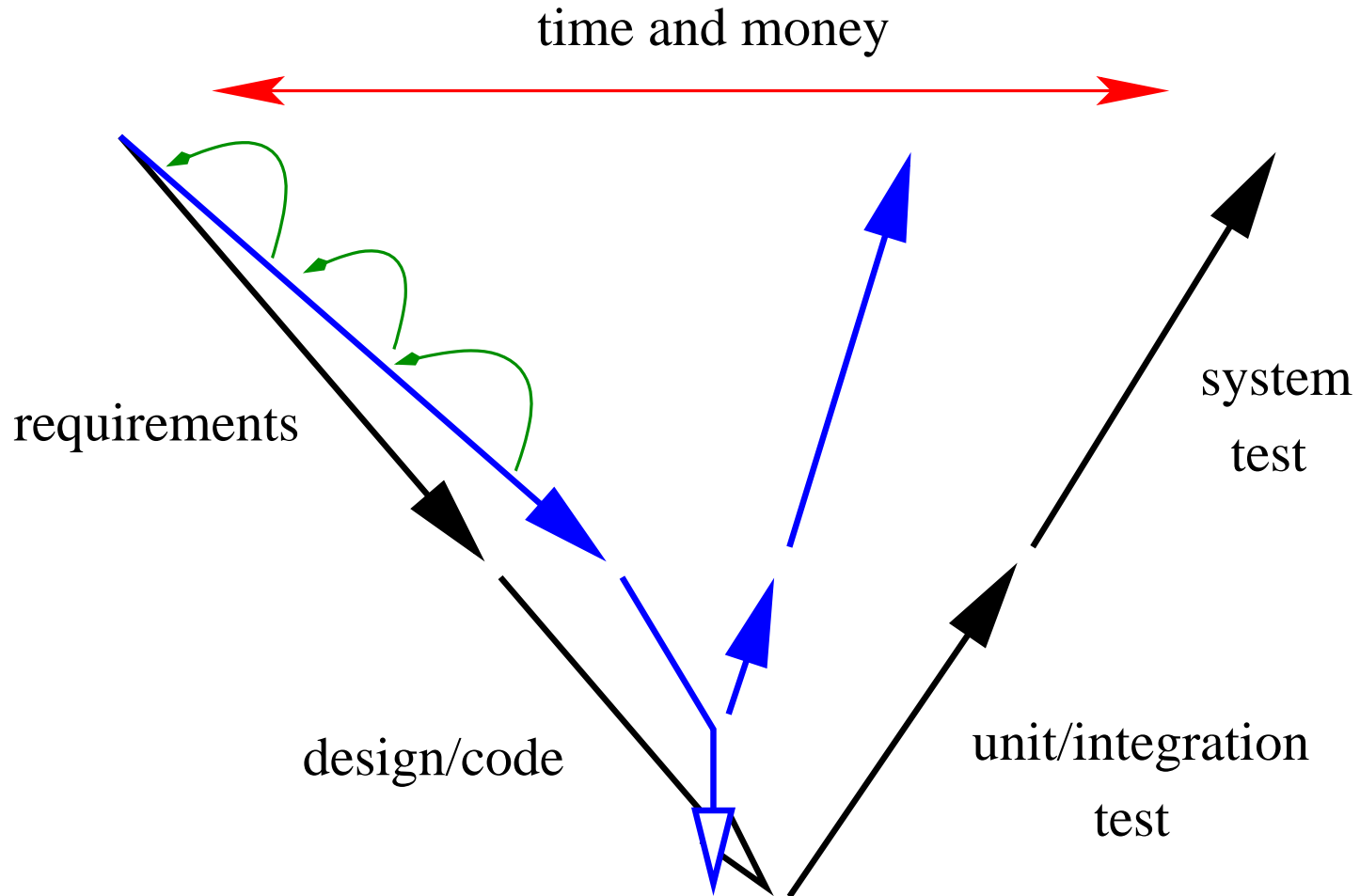
- The same reachability methods we use to **analyze** monitor-response fault management rules
- Could be used to **synthesize** the rules
 - **Supervisory controller synthesis (Ramadge and Wonham)**
 - Set up as a game between fault management and the environment
 - **Use reachability analysis to synthesize rules so that from any state, no move by the environment can force us into a losing state**
- Could be used **statically** on the ground
- Or **dynamically** onboard the spacecraft (next talk)

Overall V&V Process

Traditional Vee Diagram (Much Simplified)



Vee Diagram Tightened with Formal Analysis



Example: Rockwell-Collins

Systems and Subsystems

- The FAA certifies airplanes, engines and propellers
- Components and subsystems are certified only as part of an airplane or engine
- That's because it's the interactions that matter and it's not known how to provide assurance for these compositionally
- But modern engineering and business practices use massive subcontracting and component-based development that provide little visibility into subsystem designs
- So we are forced to contemplate compositional and incremental approaches to assurance and V&V
- Manifestation of noncompositionality in FM is the need to run tests for days or weeks to get into interesting states

Compositional and Incremental Assurance

- Compositional assurance means deriving the assurance case for the system from those of its subsystems
- Without going into all the subsystem details
- It is difficult because
 - The assurance case may not decompose along architectural lines
- Spacecraft have inherent subsystem coupling (through the plant)
- But we should surely eliminate unnecessary coupling
 - Computer to computer and bus communication issues
 - Partitioning
 - Information hiding interfaces

Computer to Computer and Bus Communications

- It's easy to mess these up
 - Bad fault modes (babbling—e.g., Clementine)
 - Timing (e.g., recent spysat?)
- It is known how to do it right (e.g., TTA, SPIDER)
- These are more than just buses—they are frameworks for integration
- That is, they facilitate compositional design

Integration Framework Anecdotes

Powertrain integration: car engines from one plant, gearboxes from another

- Typically **months** of work to get them to work together
- A few **hours** using TTA

Multi-channel FADEC integration: get single channel working, then add second channel

- Typically **months** of work to get both channels cooperating
- A few **hours** using TTA

Assurance benefits beyond those in **integration**

Partitioning

- Subsystems may share processor resources
- Don't want a fault in one subsystem to wreck others
 - By messing with its state, timing, etc.
- **Integrated modular avionics (IMA)** for aircraft use
Partitioning RTOSs
- Similar RTOSs (but with higher assurance, called **separation kernels**) used in embedded applications for high security
- Again, best seen as integration frameworks rather than just protection mechanisms

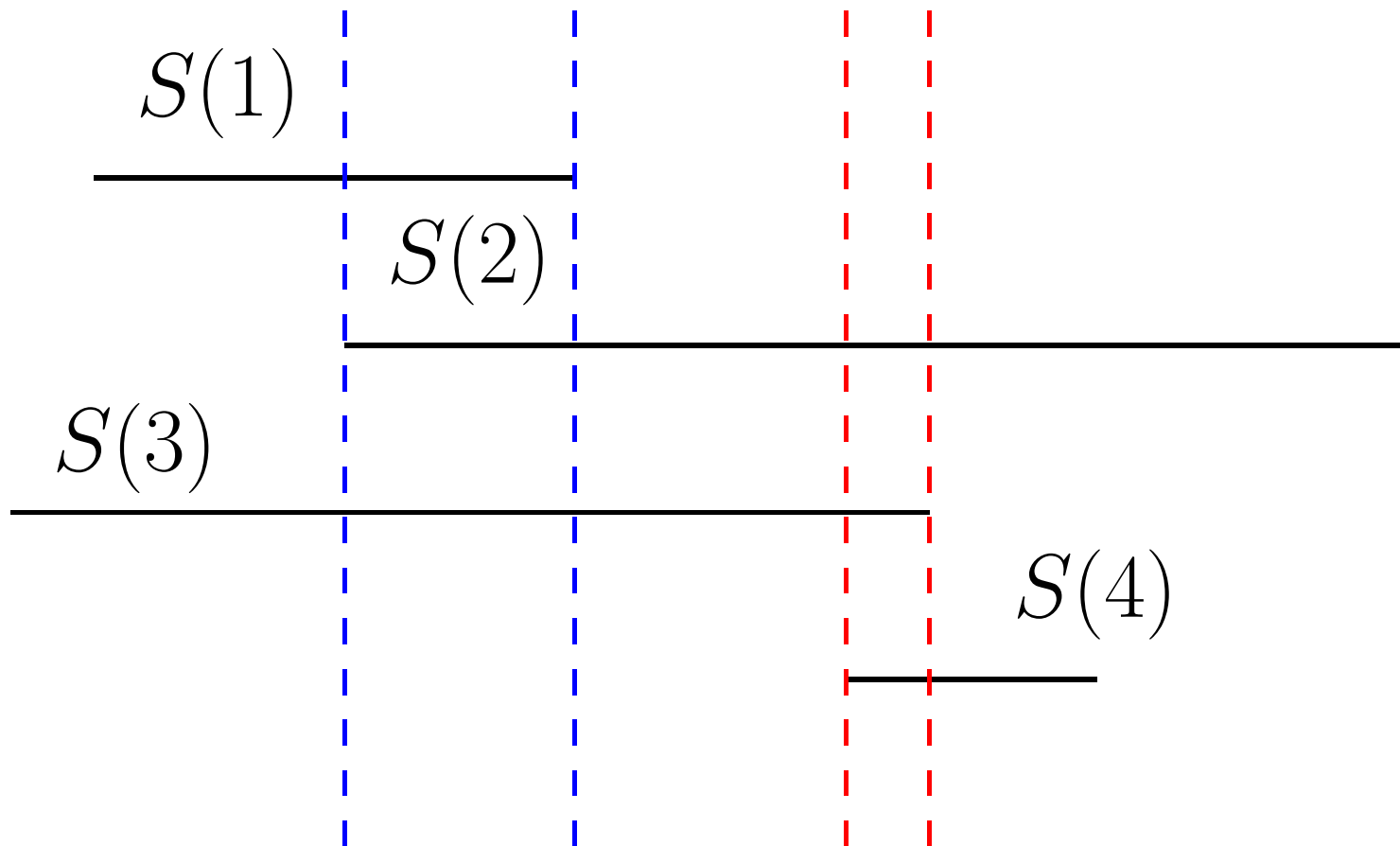
Information Hiding Interfaces

- Partitioning buses and RTOSs prevent propagation of faults
- And have the side effect of facilitating compositional design
- By eliminating unintended interactions and coupling
- We need to do this throughout the design
 - “Complexity containment regions”
 - That’s what interfaces are
 - And architecture at a higher level

Information Hiding Interfaces: Sensor Example

- Typically, send raw sensor samples with timestamp
- To integrate multiple samples, need to know the fault-status and detailed behavior of each sensor
- Use complex variants of mid-value select to mask faults
- **Instead**, we could use **intelligent sensor** (knows its own status, does local diagnosis)
- Sends sample as an **interval**: **true value guaranteed to be somewhere inside** (if nonfaulty)
 - Narrow interval when healthy, good sample; wider if not
- With a “**use by**” date
- **Known how to combine intervals, even when some are faulty**
- System does not need to know subsystem details

True Value In Overlap Of Nonfaulty Intervals



Compositional V&V

- Reachability analysis with a model checker examines whether interacting components satisfy some requirement
 - e.g, $\text{device, control, environment} \models \text{requirement}$
- We can try to find the **weakest** model **D** for the device that still does the job (might have to adjust **control**)
 - i.e., $\text{D, control', environment} \models \text{requirement}$
- Then, later, show that the real device satisfies **D**
 - i.e., $\text{device} \models \text{D}$
- So reachability tools can help develop interfaces that promote compositional assurance

Summary

- If we want to improve cost and effectiveness of V&V, we need a **framework** to help us rethink it
 - Goal based assurance cases are a promising framework
 - Explicit **claims, evidence, argument**
- Model-based design opens the door to reachability analysis
 - aka. model checking, formal methods
 - This is **automated**, can be done **early**, examines **vast numbers of behaviors** including interactions
 - Preserves the valuable high-fidelity testbed
- Strong interfaces promote compositional assurance
 - Reachability analysis can help develop these
- **Autonomy is surely the way of the future; let's get the V&V right (reliable, early, affordable; enabler, not impediment)**